# DISCRETE <br> COMMUTATIVE DIFFERENCE OPERATOR THEORY 

THESIS
SUBMITTED FOR THE DEGREE OF DOCTOR OF PHILOSOPHY

By
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## CERTIFICATE


#### Abstract

This is to certify that this thesis is a bona fide record of work by thresiamma T.K., carried out in the Department of Mathematics and Statistics, University of Cochin, Cochin 682022 under my supervision and guidance and that no part thereof has been submitted for a degree in any other University.


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## STATENENT

This thesis contains no material which has been accepted for the award of any other degree or diploma in any university and, to the best of my knowledge and belief, it contains no material previously published by any other person, except where due reference is made in the text of the thesis.

Thresiammaт.K.
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## $\underline{S} \underline{Y} \underline{N} \underline{O} \underline{S} \underline{I} \underline{S}$

This thesis is an attempt to study basic and bibasic commutative difference operators on the lines of J.I. Burchnall and T.W.Chaundy's "Commutative differential operators" [ (1) Proc. London Math. Soc. (Sec.2) 21(1923) pp 420-440, (2) Proc. Royal Soc. London (A), 118(1928), pp 557-583, (3) Proc. Royal Soc. London (A), 134(1931), pp 471-485] on the discrete $\operatorname{set}\left\{\mathrm{p}^{m} \mathrm{x}_{0}\right\}_{i}$, $\left\{q^{n} y_{0}\right\},\left\{q^{m} x_{0}, q^{n} y_{o}\right\},\left\{p^{m} x_{0}, q^{n} y_{0}\right\} m, n \in z$, where $p, q$ are positive real constants called bases, $p \neq q \neq 1$. Also bibasic pseudo-analytic functions are introduced using two bases $p$ and $q$.

Though commutative differential operators play an important role in analysis, no basic or bibasic theory is available. This thesis is an attempt in this direction.

In the first chapter an outline of the theory of commutative differential operators done by Burchnall and Chaundy in the classical case is given. A historical survey of the study of q-difference equations, q-analytic function theory of C.J. Harman [A discrete analytic
the ory for geometric difference function, Ph.D. thesis of Adelaide (1972)], bibasic analytic functions of Khan M.A ["Contributions to the theory of generalized basic hypergeometric series, Ph.D. thesis, University of Lucknow], bianalytic functions of K.K.Velukutty [" Discrete bianalytic functions" Proc. Nat. Acad. Sci. India, 52(A), I, 1982], Discrete Pseudoanalytic functions of Mercy $\mathbf{K}$ Jacob [" Study of discrete Pseudoanalytic functions" , Ph.D. thesis, University of Cochin, 1983] and the recent works already done by others have been stated. A list of the results established in the thesis is also given.

The second chapter deals with definition of basjic difference operators, characteristic identity of twc commutative basic difference operators and the specific nature of commatative difference operators. If

$$
P_{m}=\sum_{k=0}^{m} a_{k} \theta^{k}, Q_{n}=\sum_{k=0}^{n} b_{k} \theta^{k}
$$

then we arrive at the results that if $a_{k}$ and $b_{k}$ are constants or $q$-periodic functions of $x$ then $P_{m}$ and $Q_{n}$ are commutative. But if they are variable functions of x they are commutative. Hence we find the conditions
for which these commute. We see that there are some relationships between the coefficients $a_{k}(x)$ and $b_{k}(x)$ which make the operators commute with each other. Some examples are constructed. Then we arrive at the result that the difference operators $P$ and $Q$ are commatative if and only if $F(P, Q)=0$.

Some special commutative operators are developed in the third chapter. Taking $\delta=x \theta, \theta^{n}$ is factorised by means of $\delta$. If two operators have a common factor, by transference of that factor we obtain new operators. And we show that if $P^{\prime}$ and $Q^{\prime}$ are the new operators obtained by transference of common factor of $P$ and $Q$ respectively then $F(P, Q)=F\left(P^{\prime}, Q^{\prime}\right)$. We get the result $f(\delta) x^{a}=f([a]) x^{a}$, and find the inverse $f\left(\delta^{-1}\right) x^{a}=f\left(\frac{1}{[a]}\right) x^{a}$. Using these results some q-difference equations are solved.

In the fourth chapter we define basic adjoint operators and their properties are listed. If $P$ and $Q$ are commutative, their adjoints also are commutative. The same results are obtained for transference also. Then it is shown that if a linear operator commutes with an operator $P$, it is a polynomial in that operator.

The bibasic commutative difference operators are studied by considering functions of $x$ and $y$ in $R^{2}$. Definitionsof $D_{p x}$ and $D_{q y}$ with bases $p$ and $q$ and their proporties studied in the fifth chapter. Some special bibasic commutative difference operators are taken and some bibasic difference equations are solved.

The last chapter deals with bibasic pseudoanalytic functions and their properties. Pseudoanalytic functions of Mercy, bibasic analytic functions of Khan, bianalytic functions of K. K.Velukutty, and q-analytic functions of Harman are special cases of this. Bibasic analogues of $z^{(n)}$ and bex( $\left.z\right)$ of classical power and exponential functions etc are also given as examples of such functions.

Finally some lines for further study are suggested. A bibliography containing 75 references is also given.

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## CHAPIER I


#### Abstract

The object of this thesis is to formulate a basic commutative difference operator theory for functions defined on a basic sequence, and a bibasic commutative difference operator theory for functions defined on a bibasic sequence of points, which can be applied to the solution of basic and bibasic difference equations. We give in this chapter a brief survey of the work done in this field in the classical case, as well as a review of the development of q-difference equations, q-analytic function theory, bibasic analytic function theory, bianalytic function theory, discrete pseudoanalytic function theory and finally a summary of resuıts of this thesis.


1. A BRIEF SURVEY OF KNOWN RESULTS
(a) Theory of commutative differential operators

In this section we give an outline of the work done in the theory of commutative differential operators by J.L. Burchnall and T.W.Chaundy $[1,2,3]$.

$$
\begin{equation*}
\text { Let } \varphi(D)=\alpha_{0} D^{n}+\alpha_{1} D^{n-I}+\ldots+\alpha_{n} I \tag{1.1}
\end{equation*}
$$

where $\alpha_{0}, \alpha_{1}, \ldots, \alpha_{n}$ are functions of $x$ and $D=\frac{d}{d x}$, $D^{m}=\frac{d^{m}}{d x^{m}}$, be defined as a general polynomial differential operator of finite order $n$. Hence if fis any function of $x$, differentiable $n$ times, then

$$
\begin{equation*}
\varphi(D) f=\alpha_{0} \frac{d^{n_{f}}}{d x^{n}}+\alpha_{1} \frac{d^{n-1}}{d x^{n-1}}+\ldots+\alpha_{n} f \tag{1.2}
\end{equation*}
$$

We denote such operators as $\varphi(D), \psi(D)$ etc. by $P, Q$ etc.

If $P$ and $Q$ are two operators where

$$
\begin{align*}
& P=\alpha_{0} D^{m}+\alpha_{I} D^{m-1}+\ldots+\alpha_{m} I  \tag{1.4}\\
& Q=\beta_{0} D^{n}+\beta_{1} D^{n-1}+\ldots+\beta_{n} I \tag{1.5}
\end{align*}
$$

then in general they are not commutative.

Their alternant $\mathrm{QP}-\mathrm{PQ}$ on expansion, is an operator of order not exceeding $m+n-1$. It vanishes identically if the coefficients of $f, f^{\prime}, f^{\prime \prime}, \ldots, f^{(m+n-1)}$ vanish under the condition that the $m+n$ differential equations

$$
\begin{aligned}
\binom{n}{1} \beta_{0} \alpha_{0}^{\prime} & -\left(\frac{m}{1}\right) \alpha_{0} \beta_{0}^{\prime}=0 \\
\binom{n}{2} \alpha_{0}^{n} \beta_{0} & +\binom{n}{1} \beta_{0} \alpha_{1}^{\prime}+\binom{n-1}{1} \beta_{1} \alpha_{0}^{\prime}-\left(\frac{m}{2}\right) \alpha_{0} \beta_{0}^{\prime \prime} \\
& -\left(\frac{m}{1}\right) \alpha_{0} \beta_{1}^{\prime}-\left(\frac{m-1}{j}\right) \alpha_{1} \beta_{0}^{\prime}=0
\end{aligned}
$$

$$
\begin{gathered}
\beta_{o} \alpha_{m}^{(n)}+\beta_{1} \alpha_{m}^{(n-1)}+\ldots+\beta_{n-1} \alpha_{m}^{\prime}-\alpha_{o} \beta_{n}^{(m)} \\
-\alpha_{1} \beta_{n}^{(m-1)} \ldots-\alpha_{m-1} \beta_{n}^{\prime}=0
\end{gathered}
$$

are satisfied. However, all polynomial differential operators with constant coefficients are commutative.

Hence study of commutative differential operators results in a functional rulation between the operators which is called the characteristic identity.

Eliminating $D^{t} y(t=0,1, \ldots, m+n-1)$ from

$$
\begin{align*}
& D^{r}(P-h I) y=0(r=0,1, \ldots, n-1)  \tag{1.6}\\
& D^{s}(Q-k I) y=0(s=0,1, \ldots, m-1) \tag{1.7}
\end{align*}
$$

an algebraic relation

$$
\begin{equation*}
F(h, k)=0 \tag{1.8}
\end{equation*}
$$

is obtained

Hence if $P$ and $Q$ are commutative then

$$
\begin{equation*}
F(P, Q)=0 \tag{1.9}
\end{equation*}
$$

and conversely if a relation $F(P, Q)=0$ can be found then $P, Q$ commute.

Transformation of common factors of $P$ and $Q$ results in new operators $P^{\prime}$ and $Q^{\prime}$ and also

$$
\begin{equation*}
F(P, Q)=F\left(P^{\prime}, Q^{\prime}\right) \tag{1.10}
\end{equation*}
$$

Thus the characteristic identity $F(P, Q)=0$ remains invariant for the whole set of operators derived from a chosen $P, Q$. So restricted, the operators form a group.

$$
\begin{align*}
& \text { Defining the adjoint of } \\
& P=\sum_{k=0}^{m} a_{k}(x) D^{k} \text { as } P^{*}=\sum_{k=0}^{m}(-D)^{k} a_{k}(x) \tag{I.II}
\end{align*}
$$

T.W.Chaundy [I] proved that if $P^{*}, Q^{*}$ are the adjoints of $P$ and $Q$ respectively, then

$$
\begin{equation*}
F(P, Q)=F\left(P^{*}, Q^{*}\right) \tag{1.12}
\end{equation*}
$$

J.I. Burchnall and T.W. Chaundy [I] also defined another type of operators with $\delta=x D$ whose examples are

$$
\begin{align*}
& P=x^{-m} \delta(\delta-n I)(\delta-2 n I) \ldots(\delta-(m n-n) I)  \tag{1.13}\\
& Q=x^{-n} \delta(\delta-m I)(\delta-2 m I) \ldots(\delta-(m n-m) I) . \tag{1.14}
\end{align*}
$$

Later T.W.Chaundy [2] solved many ordinary differential equations using $\delta$. Analogously differential operators

$$
\begin{equation*}
\varphi\left(\partial_{1}, \partial_{2}, \ldots, \partial_{n}\right)=\Sigma \alpha \partial_{1}^{a} \partial_{2}^{b} \ldots \partial_{n}^{k} \tag{1.15}
\end{equation*}
$$

with $\partial_{r}=\frac{\partial}{\partial_{x_{r}}}$ in the field of $n$ independent variables $\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ were studied.
H. Flanders [I], S.A.Amitsur [I] and others studied on commutative linear differential operators. V.P.Maslov [1] developed an operator theory considering the differential operator $P(x, D)$ and giving an order $P\left(x^{2}, D^{l}\right)$ showing $D$ acts first.

Later Coddington $[1,2,3]$ elaborated the theory of formal normal operators. Recently Hahn [5] has given an algebraic approach to commutative linear differential operators.

Eventhough much work has been done in this field, no basic or bibasic theory is available in literature.
(b) q-difference equations

A very extensive development of the theory of q-difference equations was carried by Jackson $[1,2,3,4,5]$. In 1908 Jackson used the difference operator

$$
\begin{equation*}
\theta \varphi(x)=\frac{\varphi(q x)-\varphi(x)}{(q-1) x} \tag{1.16}
\end{equation*}
$$

which gave rise to a series in which the coefficients follow the q-binomial form. In 1910 he introduced the concept of q-integration which he defined as the inverse q-difference operator $\theta$, as

$$
\begin{equation*}
\theta_{x}^{-1} f(x)=\frac{1}{1-q} \subseteq f(x) d(q, x) \tag{1.17}
\end{equation*}
$$

Hahn [1] and Jackson [5] studied fundamental properties of the inverse operation, showing that under certain conditions, the q-integral tends to the Riemann integral as $q \rightarrow \rightarrow$. In fact the definite $q$-integrals are defined by

$$
\int_{0}^{x} \theta_{x} f(x) d(q, x)=f(\infty)-f(0)
$$

$$
\begin{equation*}
\int_{x}^{\infty} \theta_{x} f(x) d(q, x)=f(\infty)-f(x) \tag{1.19}
\end{equation*}
$$

whence

$$
S_{a}^{b}=S_{0}^{b}-S_{0}^{a}
$$

Correspondingly the q-integrals can be defined by

$$
\begin{equation*}
\int_{0}^{x} f(y) d(q, y)=(l-q) x \sum_{j=0}^{\infty} q^{j} f\left(q^{j} x\right) \tag{1.20}
\end{equation*}
$$

$$
\begin{equation*}
\int_{x}^{\infty} f(y) d(q, y)=(1-q) x \sum_{j=1}^{\infty} q^{-j} f\left(q^{-j} x\right) \tag{1.21}
\end{equation*}
$$

$$
\begin{equation*}
\int_{0}^{\infty} \dot{f}(y) d(q, y)=(1-q) \sum_{j=-\infty}^{\infty} q^{j} f\left(q^{j}\right) \tag{1.22}
\end{equation*}
$$

Among other results Jackson deduced the formula for q-integration by parts

$$
\begin{align*}
& S\left\{\theta_{x} f(x)\right\} g(x) d(q, x)=(1-q) \\
& f(x) g(x)  \tag{1.23}\\
&-S f(q x)\left\{\theta_{x} g(x)\right\} d(q, x)
\end{align*}
$$

In 1960, Abdi $[1,2,3,4)$ revived interest in q-integration when he made a thorough study of
q-Laplace transforms which were applied to the solution of certain q-difference and q-integral equations. Al-Salam [I] and Agarwal [2] in 1969 obtained qanalogues of Cauchy's multiple integral formula and fractional q-integrals.

> Apart from these results in q-integration, research in $q$-difference theory has divided into two main streams, number theory and the general theory of q-difference equations.

Carmichael [1,2], Adams [5] and Tritzinsky [I], amongst others have evolved an extensive theory for linear q-difference equations. In 1943 Sawyer [I] studied the system $(F-\lambda G)=0$ for second order and Chaundy $[3,4]$ considered the general case. M.Upadhyay[I] solved q-difference equation of first order of Sawyer's type. Important contributions have been made by Hahn $[2,3,4]$ and Abdi [2].

Abdi $[5,6,7]$ introduced a 'bibasic' functional equation of the form $a(z) f(p z)+b(z) f(q z)$ $+c(z) f(z)=0$. He has also solved some bibasic functional equations.

## (c). q-analytic function theory

In 1972 Harman [I] developed a discrete analytic theory for geometric difference functions.

He defined a lattice with geometric spacing, ie. points of the form

$$
\begin{equation*}
H=\left\{\left( \pm q^{m} x_{0}, \pm q^{n} y_{0}\right) ; m, n \varepsilon z\right\} \tag{1.24}
\end{equation*}
$$

where $0<q \leqslant I$ and $x_{0}>0, y_{\sigma}>0$ are fixed numbers. Complex valued functions defined on the points of $H$ are called discrete functions. Functions satisfying

$$
\begin{equation*}
\frac{f(x, y)-f(q x, y)}{(1-q) \dot{x}}=\frac{f(x, y)-f(x, q y)}{(1-q) i y}=L[f(z)] \tag{1.25}
\end{equation*}
$$

where $z=(x, y) \varepsilon H$, are called $q$-analytic functions. Hence the operator $L$ is defined by

$$
\begin{equation*}
L[f(z)]=\bar{z} f(z)-x f(x, q y)+i y f(q x, y) \tag{1.26}
\end{equation*}
$$

Defining a discrete domain $D$, he defined the q-analyticity of a discrete function $f(z)$ in D. If $L[f(z)]=0$ for every $z \varepsilon D$ such that $T(z)=$ $\{(x, y),(q x, y),(x, q y)\}$ C $D$, then $f(z)$ is $q$-analytic
in $D$. He also obtained the properties of q-analytic
functions in D. As exampies of q-analytic functions, he defined

$$
\begin{align*}
z^{(n)} & =\sum_{j=0}^{n}\binom{n}{j}_{q} x^{n-j}(i y)^{j}  \tag{1.27}\\
e_{q}!(z) & =\sum_{j=0}^{\infty} \frac{(1-q)^{j}}{(1-q)_{j}} z^{(j)} \tag{1.28}
\end{align*}
$$

and discussed their properties.
(d). Bibasic analytic functions

Khan M.A [1] studied bibasic analytic functions choosing the lattice

$$
\begin{equation*}
\left\{\left(p^{m} x_{0}, q^{n} y_{0}\right) ; m, n \in z\right\}, p \neq q \neq 1 \tag{1.29}
\end{equation*}
$$

and defining a discrete domain. He defined the bibasic difference operators $D_{p x}, D_{q y}$, as

$$
\begin{align*}
& D_{p x} f(z)=\frac{\left.f(z)-\frac{f(p x, y)}{(1-p) x}\right)}{D_{q y} f(z)=\frac{f(z)-f(x, q y)}{(1-q) i y}} \tag{1.30}
\end{align*}
$$

where $f(z)$ is a discrete function. Hence, if

$$
\begin{align*}
& T^{\prime}(z)=\{(x, y),(p x, y),(x, q y)\} \text { and } \\
& D_{p x}=D_{q y} f(z) \tag{1.32}
\end{align*}
$$

such that $T^{\prime}(z) C D$, then $f(z)$ is said to be bibasic analytic at $z \varepsilon D$. If (1.32) holds for every $z \varepsilon D$, then $f(z)$ is said to be bibasic analytic in $D$.

Let $L^{\prime}[(f(z)]=\{\bar{z}-p x+q i y\} f(z)-(I-p) x f(x, q y)$

$$
\begin{equation*}
+(1-q) i y f(p x, y) \tag{1.33}
\end{equation*}
$$

Therefore $f(z)$ is bibasic analytic in $D$ if and only if

$$
\begin{equation*}
L^{\prime} f(z)=0 \tag{1.34}
\end{equation*}
$$

for every $z \varepsilon D$. He has given the properties of bibasic analytic functions and constructed examples of bibasic analytic functions, where

$$
\begin{equation*}
z^{(n)}=\sum_{j=0}^{n} \frac{(p)_{n}}{(p)_{n-j}(q)_{j}}\left\{\frac{(1-q) i y}{1-p}\right\}^{j} x^{n-j} \tag{1.35}
\end{equation*}
$$

$$
\begin{align*}
o_{1} M_{1}[-; p ; z] & =\sum_{n=0}^{\infty} \frac{z^{(n)}}{(p)_{n}}  \tag{1.36}\\
& \left.=e_{p}(x) \text { eq( } \frac{i y(1-q)}{1-p}\right) \tag{1.37}
\end{align*}
$$

According to Khan's definition

$$
\begin{equation*}
D_{p x^{z}}{ }^{(n)}=D_{q y^{z}}(n)=\left(\frac{1-p^{n}}{1-p}\right) z^{(n-1)} \tag{1.38}
\end{equation*}
$$

The theory of bibasic analytic functions is a two fold extension of the theory of q-analytic functions. The presence of two bases gives more freedom of the choice of the bases.

## (e). Bianalytic functions

> Velukutty [I] defined bianalytic functions
taking the lattice
$H=\left\{\left(q^{m} x_{0}, q^{n} y_{0}\right), m, n \in z\right\}, 0<q<1,\left(x_{0}, y_{0}\right)$ are fixed, $x_{0}>0, y_{0} \geqslant 0$, and $p=q^{-1}$.

He defined two operators $R_{q}$ and $R_{p}$ as

$$
\begin{align*}
& R_{q} f(z)=\bar{z} f(x, y)-x f(x, q y)+i y f(q x, y)  \tag{1.40}\\
& R_{p} f(z)=\bar{z} f(x, y)-x f(x, p y)+i y f(p x, y) \tag{1.41}
\end{align*}
$$

where $f: H \longrightarrow \not \subset$
$R_{q} f(z)$ and $R_{p} f(z)$ are respectively called the $q$ - and p - residues of the function $f$ at $z$. If the $q$-residue (p-residue) of $f$ is zero at $z, f$ is said to be q-analytic (p-analytic) at $z$. A function $f: H \longrightarrow \varnothing$ which is both q- and p- analytic in D (a discrete domain) is called bianalytic in D. In fact, it satisfies the equation (1.42)

$$
\begin{equation*}
R_{q} f(z)=R_{p} f(z)=0 \text { everywhere in } D . \tag{1.43}
\end{equation*}
$$

He has discussed the properties of bianalytic functions and how to construct bianalytic functions giving examples. $f(z)=\alpha z+\beta, \alpha, \beta \varepsilon \not \subset$ is a trivial example of a bianalytic function in entire $H$.

## (f). Pseudo-analytic functions

Mercy K. Jacob [I] introduced pseudo-analytic functions on the lattice,

$$
\begin{align*}
& \left\{\left(q^{m} x_{0}, q^{n} y_{0}\right), m, n \varepsilon z\right\}, 0<q<1, x_{0}>0, y_{0}>0 \\
& \text { are fixed numbers. } \tag{1.44}
\end{align*}
$$

The theory of discrete pseudoanalytic functions is a generalisation of the theory of q-analytic functions. Discrete functions satisfying the inequality

$$
\begin{equation*}
\left|f(z)-f\left(z^{\prime}\right)\right| \leqslant k \sigma^{\mu} \tag{1.45}
\end{equation*}
$$

where $z^{\prime}=\left(x^{\prime}, y^{\prime}\right) \varepsilon D$, a discrete domain, $z \varepsilon A\left(z^{\prime}\right)$;

$$
A\left(z^{\prime}\right)=\left\{\left(q x^{\prime}, y^{\prime}\right),\left(x^{\prime}, q y^{\prime}\right),\left(q^{-1} x^{\prime}, y^{\prime}\right),\right.
$$

$$
\begin{equation*}
\sigma=\left(q^{-1}-1\right) \max \left(x^{\prime}, y^{\prime}\right), \quad 0<\mu \leqslant 1 \tag{1.46}
\end{equation*}
$$

have been called discrete Hölder-type at z' $\varepsilon$ D.

If the above inequality holds for all $z \varepsilon D$ then the function is called discrete Hölder-type in D, denoted as $H(D)$. If $g_{1}, g_{2} \varepsilon H(D)$ such that $\operatorname{Im}\left(\bar{g}_{1}, g_{2}\right)>0$, then the row vector $g=\left[g_{1}, g_{2}\right]$ is called a generating vector. If $f=\left[f_{1}, f_{2}\right]^{\prime}$ where $f_{1}$ and $f_{2}$ are real valued functions in $D$, we call the set of all such column vectors $F(D)$.

Suppose $g=\left[g_{1}, g_{2}\right] \varepsilon G(D)$ and $W \varepsilon G . F(D)$, then

$$
\begin{align*}
& g^{\theta} \mathrm{xw}(z)=\left(g \cdot \theta_{x^{-}}\right)(z)  \tag{1.47}\\
& g^{\theta} y w(z)=\left(g \cdot \theta_{y} f\right)(z) \tag{1.48}
\end{align*}
$$

If $w$ is a complex valued function defined in $D$, then w is called discrete g-pseudoanalytic of the first kind at $z \varepsilon D, i f$

$$
\begin{equation*}
w \varepsilon G \cdot F(D) \text { and } g^{\Theta} x w(z)=g^{\Theta} y w(z) \text {. } \tag{1.49}
\end{equation*}
$$

If this relation holds for all $z \varepsilon D$, then $w$ is called g-pseudoanalytic of the first kind in $D$, the class of such functions denoted by ${ }_{I} P_{D}(g)$.

If

$$
\begin{equation*}
\mathrm{w}=(\mathrm{g} . f), f \varepsilon \mathrm{f}(\mathrm{D}), \mathrm{g} \varepsilon G(D) \tag{1.50}
\end{equation*}
$$

W $\varepsilon_{1} P_{D}(g)$, then $h=f_{1}+i f_{2}$ is discrete g-pseudoanalytic of the second kind in $D$. The class of discrete g-pseudoanalytic functions of the second kind in $D$ is denoted by ${ }_{2} P_{D}(g)$.

## 2. SUMMARY OF RESULTS OF THE THESIS

Along with the above brief survey of work done in the field of differential operators, q-difference theory, q-analytic theory, bibasic analytic functions, bianalytic functions and pseudoanalytic functions, it
is worth mentioning that ro work has been done in basic commutative difference operators, bibasic commutative difference operators and bibasic pseudoanalytic functions. Hence an attempt is made in this thesis on these lines. Now we give the summary of results here.

Using the concept of differential operators defined and developed by J.L.Burchnall and T.W.Chaundy $[1,2,3]$, a basic the ory has been developed for functions defined on the $\operatorname{set}\left\{q^{m} x_{0}, m \varepsilon z\right\}, 0<q<1, x_{0}>0$ are fixed and accordingly the conditions for basic difference operators to be commutative have been established. Some examples are also given. Then we try to establish some properties of these operators. Considering two operators $P_{m}$ and $Q_{n}$, their characteristic identity is obtained. We see that two operators $P_{m}$ and $Q_{n}$ are commutative if and only if there is an algebraic relation of the form $f\left(P_{m}, Q_{n}\right)=0$. This is the content of Chapter Two.

The Third Chapter deals with some special basic commutative difference operators $\delta=x \theta$, and their properties. We are able to obtain commutative difference operators easily using these $\delta$. Given a pair of commutative difference operators, we shall form new pairs by transference of common factors if any, and hence we
can find that a set of q-difference equations is generated by the same characteristic identity. If $f(\delta)$ is a polynomial operator in $\delta$, we define $f\left(\delta^{-1}\right)$ and prove some theorems connected to these polynomial operators. Applying these operators and results related to them, we solve some basic difference equations.

In the Fourth Chapter we use concepts of J.L.Burchnal and T.W.Chaundy [1] and Coddington [1,2,3] to develop basic adjoint operators, normal operators, and self-adjoint operators. Here we prove that if the coefficients are constants or q-periodic iunctions of x , then the basic operator is normal. When the coefficients are not constants or q-periodic functions, then we see that an operator $P$ in general is not a normal operator. But we could not obtain a complete characterisation. We also see that if a first order basic difference operator $Q$ commutes with an operator $P$ of order $m$, then $P$ is a polynomial in that operator $Q$. We conclude this chapter by giving some applications of adjoint operators.

Abdi [5,6,7] introduced the concept of bibasic functional equations. The Fifth Chapter is an attempt
to define bibasic difference operators $D_{p x}$ and $D_{q y}$. We study the effect of action of these operators on functions $f(x, y)$ defined on $R^{2}$. Also we discuss the nature of these operators and conditions under which they commute. Considering 'Jibasic difference operators of the form

$$
P_{m}=\sum_{k, j=0}^{m} a_{k, j} D_{p x}^{k} D_{q y}^{j}(.), k+j \leqslant m
$$

Some special bibasic operators also are considered and their properties established. We see that the alternant of two linear operators is also a linear operator and hence we are able to form repeated alternants of such operators. Finally, we solve some bibasic difference equations in $R^{2}$.

The last chapter starts with the definition of functions which are pseudoanalytic in certain domain in the discrete geometric space with two unconnected bases p and q . We try to establish some of their properties. We see that this theory reduces to that of basic pseudoanalytic functions, bibasic analytic functions, bianalytic functions and q-analytic functions under certain conditions. We also define $z(n)$ and bex( $z$ ) in the
bibasic case. However, these are examples of bibasic analytic functions which are different from those of Khan [I], where $D_{p x} Z^{(n)}$ and $D_{q y}{ }^{(n)}$ are given in terms of $p$ alone. But in the new definition of $z^{(n)}$ we get these in terms of both $p$ and $q$. We also show that continuation from both the axes is possible by taking suitable continuation operators. Finally, we establish an analogue of Maclaurin series.

There are some interesting problems related to these theories like study of integral curves and second degree partial difference equations which we have not attempted here.

## CHAPTER-II

BASIC COMMUTATIVE DIFFERENCE OPERATORS

In this chapter we study different types of basic commutative difference operators (ie. commutative q.difference operators) and their behaviour when the coefficients are constants, q-periodic functions of $x$ or variable functions of $x$ which satisfy certain conditions. In general, all operators are not commutative. Hence an attempt is made here to determine the operators which commute with each other. Also we show that two operators $P_{m}$ and $Q_{n}$ are commutative if and . oniy if they satisfy a functional equation $F\left(P_{m}, Q_{n}\right)=0$.

1. BANTC DIFFERENCE OPERATORS

Here we consider the difference operator $\theta$ on rคn? valued functions of a variable $x$, where

$$
\begin{align*}
& \theta \varphi(x)=\frac{\varphi(x)-\varphi(q x)}{(1-q) x} \text {, Jackson [1] and }  \tag{2.1}\\
& \theta^{r}\lceil\varphi(x) g(x)]=\sum_{j=0}^{r}\binom{r}{j} q_{q}^{j(j-r)} \theta^{j} \varphi\left(q^{r-j}\right) \theta^{r-j} g(x),  \tag{2.2}\\
& \text { Hahn [4] } \\
& \begin{array}{l}
\binom{r}{j}_{q}=\frac{(1-q)_{r}}{(1-q)_{j}(1-q)_{r-j}} \\
(1-q)_{r}=(1-q)\left(1-q^{2}\right) \ldots\left(1-q^{r}\right) .
\end{array} \tag{2.3}
\end{align*}
$$

Accordingly we derine the general basic polynomial difference operator of order $m$.

$$
\begin{equation*}
P_{m}=\sum_{k=0}^{m} a_{k} \theta^{k} \tag{2.4}
\end{equation*}
$$

where $a_{k}$ are constants or finctions of $x, x=q^{\alpha} x_{0}$, $q \varepsilon(0, I), x_{o}>0$ fixed $\alpha \in Z$ and $a_{m} \neq 0$.

We also define

$$
\begin{aligned}
P & =\sum_{k=0}^{\infty} a_{k} \theta^{k}=\sum_{m \rightarrow \infty}^{\lim } \sum_{k=0}^{m} a_{k} \theta^{k} \\
& =\lim _{m \rightarrow \infty} P_{m} \quad \text {, in the usual sense. }
\end{aligned}
$$

$$
f(x)=\sum_{k=0}^{m} a_{k} x^{k},|x|<x_{0}, x=q^{\alpha} x_{0}, \quad 0<q<1
$$

$\alpha \varepsilon Z, X_{o}>c, a_{k}$ constants or variable functions of $x$ is called the associated polynomial.

If $m$ is infinite, question of convergence will
arise involving both the operand and the coefficients. We cannot discuss the convergence of the operator by itself without a knowledge of the operand. If the operand is merely a polynomial in $x$ of $n^{\text {th }}$ degree, the infinite operators terminate at $\theta^{n}$. In other cases, if we consider infinite operators we have to make restrictions.

It is easily seen that such operators can be combined by the algebraic operations of addition, subtraction and multiplication.

If $P_{m}$ and $Q_{n}$ are two basic difference operatcrs, then we define the addition and multiplication as;

$$
\begin{align*}
& \left\{P_{m} \pm Q_{n}\right\} f=P_{m} f \pm Q_{n} f  \tag{2.5}\\
& \left\{P_{m} Q_{n}\right\} f=P_{m}\left\{Q_{n} f\right\} \tag{2.6}
\end{align*}
$$

We see from (2.5) and (2.6) that the basic difference operators follow the fundamental laws of arithmetical combination except possibly the commutative law of multiplication.

## 2. BASIC COMMUTATIVE DIFFERENCE OPERATORS

Two operators are said to be commutative if they watisfy the commutative law of multiplication. In other words, if

$$
\begin{aligned}
P_{m}= & \sum_{k=0}^{m} a_{k} \theta^{k} \text { and } Q_{n}=\sum_{k=0}^{n} b_{k} \theta^{k} \\
& a_{m} \neq 0, b_{n} \neq 0
\end{aligned}
$$

are two basic difference operators of order $m$ and $n$
respectively, they are commutative if

$$
\begin{equation*}
P_{m} Q_{n}=Q_{n} P_{m} \tag{2.7}
\end{equation*}
$$

We now inquire what sort of basic difference operators are commutative
(a) Operators $P_{m}$ and $Q_{n}$ commute if $a_{k}$ and $b_{k}$ are constants:
(i) Let $m, n$ be finite

$$
\begin{aligned}
P_{m} Q_{n} & =\left(\sum_{k=0}^{m} a_{k} \theta^{k}\right)\left(\sum_{k=0}^{n} b_{k} \theta^{k}\right) \\
& =\sum_{r=0}^{m+n} C_{r} \theta^{r}, \text { where } C_{r}=\sum_{j=0}^{r} a_{j} b_{r-j} \\
& =Q_{n} P_{m}
\end{aligned}
$$

Hence the result.
(ii) Let man be infinite,

$$
\begin{aligned}
P Q & =\left(\sum_{k=0}^{\infty} a_{k} \theta^{k}\right) \quad\left(\sum_{k=0}^{\infty} b_{k} \theta^{k}\right) \\
& =\sum_{r=0}^{\infty} C_{r} \theta^{r} \text { where } C_{r}=\sum_{j=0}^{r} a_{j} b_{r-j} \\
& =Q P .
\end{aligned}
$$

Both sides will exist if for
$\sum_{k=0}^{\infty} a_{k} x^{k}$ and $\sum_{k=0}^{\infty} b_{k} x^{k}$ the radii of convergence are
$P_{1}, P_{2}$ respectively and $\theta^{(k)} f(x)=O\left(x^{k}\right)$. Then the radius of convergence of the product series will be $\min \left(P_{1}, P_{2}\right)$. Therefore for infinite $m, n$ and also when the associated series converges and the operand is bounded, the operators are commutative.
(b) Operators $P_{m}$ and $Q_{n}$ commute if $a_{k}$ and $b_{j}$ are q-periodic functions of $x$.

Let

$$
P_{m}=\sum_{k=0}^{m} a_{k}(x) \theta^{k}, Q_{n}=\sum_{j=0}^{n} b_{j}(x) \theta^{j}
$$

Then

$$
\begin{align*}
\left(P_{m} Q_{n}\right) f= & \sum_{k=0}^{m} a_{k}(x)\left(\sum_{j=0}^{n} \sum_{i=0}^{k}\binom{k}{i} q^{i(i-k)}\right. \\
& \left.\theta^{i} b_{j}\left(q^{k-i} x\right) \theta^{k+j-i_{f}}\right)  \tag{2.8}\\
\left(Q_{n} P_{m}\right) f= & \sum_{j=0}^{n} b_{j}(x)\left(\sum _ { k = 0 } ^ { m } \sum _ { i = 0 } ^ { j } \left(\begin{array}{l}
j \\
i
\end{array} q_{q} q^{i(i-j)}\right.\right. \\
& \left.\theta^{i} a_{k}\left(q^{j-i} x\right) \theta^{j+k-i_{f}}\right) . \tag{2.9}
\end{align*}
$$

Since $a_{k}(x), b_{j}(x)$ are $q$-periodic functions of $x$, we have

$$
\begin{aligned}
& a_{k}(x)=a_{k}(q x) \ldots=a_{k}\left(q^{n} x\right), \mp k=0, \ldots m \\
& b_{j}(x)=b_{j}(q \dot{x}) \ldots=b_{j}\left(q^{m} x\right), \mp j=0, \ldots n \\
& \theta a_{k}(x)=0 b_{j}(x)=0
\end{aligned}
$$

Therefore (2.8) reduces to

$$
P_{m} Q_{n}(f)=\sum_{k=0}^{m} a_{k}(x) \sum_{j=0}^{n} b_{j}(x) \theta^{k+j}
$$

$$
=\sum_{k=0}^{m} a_{k}(x) \theta^{k} \sum_{j=0}^{n} b_{j}(x) \theta^{j}(f)
$$

$$
=\sum_{r=0}^{m+n} C_{r} \theta^{r_{f}}
$$

where $\quad C_{r} \quad=\sum_{j=0}^{r} a_{j}(x) b_{r-j}(x)$

$$
=Q_{n} P_{m}(f) \text {, from (2.9). }
$$

Hence $P_{m}$ and $Q_{n}$ commute.
A similar argument applies when $m$ and $n$ are infinite, since $q$-periodic functions $a_{k}(x), b_{j}(x)$ remain constant at all points of the set $\left\{q^{\alpha} x_{0}, \alpha \varepsilon z\right\}, x_{0}>0$ and $0<q<1$ fixed.
(c) Basic difference operators $P_{m}$ and $Q_{n}$ with coefficients $a_{k}(x), b_{j}(x)$ not q-periodic functions of $x$ and $m, n$ finite are in general, not comrutative.

They commute if the condition that $m+n+1$ basic difference equations are satisfied.

Let $\quad P_{m}=\sum_{k=0}^{m} a_{k}(x) \theta^{k}, Q_{n}=\sum_{j=0}^{n} b_{j}(x) \theta^{j}$.
Therefore,

$$
\begin{aligned}
P_{m} Q_{n}(f)= & \sum_{k=0}^{m} a_{k}(x)\left[\sum_{j=0}^{n} \sum_{i=0}^{k}\binom{k}{i} q^{i(i-k)}\right. \\
& \left.\theta^{i} b_{j}\left(q^{k-i} x\right) \theta^{k+j-i}(f)\right] \\
Q_{n} P_{m}(f)= & \sum_{j=0}^{n} b_{j}(x)\left[\sum_{k=0}^{m} \sum_{i=0}^{j}\binom{j}{i} q^{i}(i-j)\right. \\
& \left.\theta^{i} a_{k}\left(q^{j-i} x\right) \theta^{j+k-i}(f)\right] .
\end{aligned}
$$

Therefore

$$
\begin{equation*}
Q_{n} P_{m}-P_{m} Q_{n} \neq 0 \text { in general. } \tag{2.10}
\end{equation*}
$$

Now

$$
\begin{align*}
& Q_{n} P_{m}-P_{m} Q_{n}=0 \text {, if } \\
& A(x, \theta) F=0 \text {. } \tag{2.11}
\end{align*}
$$

where $F=$ Transpose $\left(f_{0}, f_{1}, f_{2}, \ldots, f_{m+n}\right)$

$$
\begin{equation*}
f_{0}=f, f_{1}=\theta f \ldots, f_{m+n}=\theta^{m+n_{f}} \tag{2.12}
\end{equation*}
$$

and $A(x, \theta)$ is the square matrix of order $(m+n+1)$ given by

.. (2.13)
where

$$
S\left(j, b, a_{i}\left(q^{j} x\right)\right)=\sum_{k=j}^{n} b_{k}(x) \theta^{k-j} a_{i}\left(q^{j} x\right)\left({ }_{k-j}^{k}\right) q^{q^{j(j-k)}}
$$

$-S\left(j, a, b_{i}\left(q^{j} x\right)={\underset{K}{k=j}}_{m} a_{k}(x) \theta^{k-j} b_{i}\left(q^{j} x\right)(\underset{k-j}{k}) q^{q} q^{j(j-k)}\right.$.

From these $m+n+1$ basic difference equations, we get the relationship between the coefficients if they commute.
3. EXAMPLE WHICH GIVES THE RELATIONSHIP BETWEEN THE COEFFICIENTS OF THE FORM (2.11), (2.12) AND (2.13)

Consider the basic difference operators $I$ and $M$
with variable coefficients, where

$$
\begin{align*}
& L=\theta^{2}+a(x) \theta+b(x) I  \tag{2.15}\\
& M=\theta+c(x) I . \tag{2.16}
\end{align*}
$$

Let $c(x)$ be a chosen function on the set $\left\{q^{\alpha} x_{0}\right\}$,
$\alpha \varepsilon Z$ such that $c\left(q^{\alpha} x\right) \rightarrow 0$ as $\alpha \rightarrow \infty$. We try to $\alpha \varepsilon Z$ such that $c\left(q^{\alpha} x_{0}\right) \rightarrow 0$ as $\alpha \rightarrow \infty$. We try to determine $a(x)$ and $b(x)$ in terms of $c(x)$ so that $L$ and $M$ may commute.

Now formally,

$$
\begin{align*}
(I M) f= & {\left[\theta^{2}+a(x) \theta+b(x) I\right][\theta f+c(x) f] } \\
= & \theta^{3} f+\left\{c\left(q^{2} x\right)+a(x)\right\} \theta^{2} f \\
& +\left\{(1+q) q^{-1} \theta c(q x)+a(x) c(q x)+b(x)\right\} \theta f \\
& +\left\{\theta^{2} c(x)+a(x) \theta c(x)+b(x) c(x)\right\} f \tag{2.17}
\end{align*}
$$

Also,
$\left(\mathbb{V} / \mathrm{I}_{\mathrm{L}}\right) \mathrm{f}=[\theta+\mathrm{c}(\mathrm{x}) \mathrm{I}]\left[\theta^{2} f+a(x) \theta f+b(x) f\right]$

$$
\begin{align*}
= & \theta^{3} f+\{a(q x)+c(x)\} \Theta^{2} f \\
& +\{\theta a(x)+c(x) a(x)+b(q x)\} \theta f \\
& +\{\theta b(x)+c(x) b(x)\} f . \tag{2.18}
\end{align*}
$$

From (2.17) and (2.18)

$$
\begin{align*}
(L M-N L) f= & \left\{c\left(q^{2} x\right)+a(x)-a(q x)-c(x)\right\} \theta^{2} f \\
& +\left\{(1+q) q^{-1} \theta c(q x)+a(x) c(q x)+b(x)-\theta a(x)\right. \\
& -c(x) a(x)-b(q x)\} \theta f \\
& +\left\{\theta^{2} c(x)+a(x) \theta c(x)+b(x) c(x)\right. \\
& -\theta b(x)-c(x) b(x)\} f \tag{2.19}
\end{align*}
$$

Hence $I$ and $M$ are not commutative in general, but L and M will commute if $\mathrm{LM}-\mathrm{ML}=0$, ie. if the following basic difference equations are satisfied.

$$
\begin{align*}
& c\left(q^{2} x\right)+a(x)-a(q x)-c(x)=0  \tag{2.20}\\
& (I+q) q^{-1} \theta c(q x)+a(x) c(q x)+b(x) \\
& -\theta a(x)-c(x) a(x)-b(q x)=0  \tag{2.21}\\
& \theta^{2} c(x)+a(x) \theta c(x)-\theta b(x)=0 . \tag{2.22}
\end{align*}
$$

We see that (2.20), (2.21), (2.22) follow from (2.19). From (2.20)

$$
c\left(q^{2} x\right)-c(x)=a(q x)-a(x) .
$$

Therefore

$$
\begin{align*}
\frac{a(x)-a(q x)}{(1-q) x} & =\frac{c(x)-\frac{c\left(q^{2} x\right)}{(1-q) x}}{} \\
\text { ie. } \quad \theta a(x) & =\frac{c(x)-c\left(q^{2} x\right)}{(1-q) x} . \tag{2.23}
\end{align*}
$$

Integrating both sides of (2.23) we get,

$$
S \theta a(x) d(q, x)=3 \frac{c(x)-\frac{c\left(q^{2} x\right.}{}(1-q) x}{(q(q, x)}
$$

ie. $a(x)=(1-q) x \sum_{i=0}^{\infty} \frac{q^{i}\left\{c\left(q^{i} x\right)-c\left(q^{i+2} x\right)\right\}}{(1-q) q^{i} x}$,

$$
\begin{gathered}
\operatorname{by}(1 ; 20) \\
=c(x)+c(q x) \text { since } c\left(q^{\alpha} x_{0}\right) \rightarrow 0 \text { as } \alpha \rightarrow \infty .
\end{gathered}
$$

Therefore

$$
\begin{equation*}
a(x)=c(x)+c(q x) \tag{2.24}
\end{equation*}
$$

From (2.22)

$$
\begin{aligned}
\theta b(x) & =\theta^{2} c(x)+a(x) \theta c(x) \\
& =\theta^{2} c(x)+\{c(x)+c(q x)\} \theta c(x)
\end{aligned}
$$

Integrating by parts using

$$
\begin{aligned}
& S\left\{\theta_{x} f(x)\right\} g(x) d(q, x)=(1-q) f(x) g(x) \\
&-S f(q x)\left\{\theta_{x} g(x)\right\} d(q, x) \\
& \text { Jackson }[4,5]
\end{aligned}
$$

ve get

$$
\begin{aligned}
S_{\theta b}(x) d(q, x)= & S \theta^{2} c(x) d(q, x) \\
& +S_{e c(x)}\{c(x)+c(q x)\} d(q, x)
\end{aligned}
$$

## Therefore

$$
\begin{aligned}
b(x)= & \theta c(x)+(1-q) c(x)\{c(x)+c(q x)\} \\
& -G c(q x) \theta\{c(x)+c(q x)\} d(q, x)
\end{aligned}
$$

ie. $b(x)=\theta c(x)+(1-q)\{c(x)\}^{2}+(1-q) c(x) c(q x)$

$$
\begin{aligned}
& -\left\{\left\{\frac{c(x)-c\left(q^{2} x\right)}{(1-q) x}\right\} c(q x) d(q, x)\right. \\
= & \theta c(x)+(1-q)\{c(x)\}^{2}+(1-q) c(x) c(q x) \\
& -(1-q) x \sum_{i=0}^{\infty}\left[q^{i}\left\{\frac{c\left(q^{i} x\right) c\left(q^{i+1} x\right)-c\left(q^{i+2} x\right) c\left(q^{i+1} x\right)}{(1-q) q^{i} x}\right\}\right.
\end{aligned}
$$

by (1.20)

$$
\begin{aligned}
= & \theta c(x)+(1-q)\{c(x)\}^{2}+(1-q) c(x) c(q x) \\
& -c(x) c(q x)
\end{aligned}
$$

Therefore

$$
\begin{equation*}
b(x)=\theta c(x)-q c(x) c(q x)+(1-q)\{c(x)\} \tag{2.25}
\end{equation*}
$$

Thus from (2.24) ind (2.25) it is clear that we can find the coefficients $a(x)$ and $b(x)$ in terms of $c(x)$.

This example illustrates that, if two basic difference operators with variable coefficients, which are not q-periodic, commute, then some relationship exists between the coefficients.

In the general case however we get $m+n+l$ basic difference equations, from which we get the relationship between the coefficients.

We now establish some properties of the se operators.
4. PROPERTIES OF BASIC DIFFERENCE OPERATORS

Theorem 1

If $f$ is a solution of the equation
$\sum_{k=0}^{m} a_{k}(x) \theta_{f:=0, ~ t h e n ~ c f ~ i s ~ a l ~ s o ~ a ~ s o l u t i o n ~ w h e r e ~}^{k}$ is any arbitrary constant.

Proof

$$
\text { As } \theta(c f(x))=c \theta f(x)
$$

and

$$
\begin{equation*}
\theta^{r}(c f(x))=c \theta^{r} f(x) \tag{2.26}
\end{equation*}
$$

We get $P_{m}(\operatorname{cf}(x))=\sum_{k=0}^{m} a_{k}(x) \theta^{k} \operatorname{cf}(x)$

$$
\begin{aligned}
& =c \sum_{k=0}^{m} a_{k}(x) \theta^{k} f(x) \\
& =c P_{m} f(x) .
\end{aligned}
$$

## Theorem 2

If $f_{1}, f_{2}, \ldots, f_{m}$ are $m$ distinct solutions of the homogeneous equation $P_{m} f=0, c_{1} f_{1}+c_{2} f_{2}+\ldots+c_{m} f_{m}$ is a solution where $c_{1}, c_{2}, \ldots, c_{m}$ are arbitrary constants.

## Proof

$$
\begin{aligned}
P_{m}\left(c_{1} f_{1}+c_{2} f_{2}\right. & \left.+\ldots+c_{m} f_{m}\right) \\
& =c_{1} P_{m} f_{1}+c_{2} P_{m} f_{2}+\ldots+c_{m} P_{m} f_{m} \\
& =0, \text { by theorem } 1 .
\end{aligned}
$$

## Theorem 3

If $g=g_{0}(x)$ be any solution of the nonhomogeneous equation $P_{m} g=r(x)$, then if $f(x)$ is the complete primitive of $P_{m} f=0$, then $g=g_{0}(x)+f(x)$ will be the most general solution of $P_{m} g=r(x)$.

Proof

$$
\theta^{r} \text { is distributive, Jackson [I]. }
$$

Thecefore $\mathrm{P}_{\mathrm{m}}$ is distributive, where

$$
P_{m}=\sum_{k=0}^{m} a_{k}(x) \theta^{k}
$$

Therefore

$$
\begin{aligned}
P_{m}\left[g_{0}(x)+f(x)\right] & =P_{m} g_{0}(x)+P_{m} f(x) \\
& =r(x)
\end{aligned}
$$

siace

$$
P_{m} g_{0}(x) \quad=r(x)
$$

Therefore $\quad P_{m} f(x)$
$=0$
and
g
$=g_{0}(x)+f(x)$
involves m arbitrary constants.

It is, therefore, the most general solution of $P_{\mathrm{m}} g=r(x)$.

Theorem 4
$P_{m}$ and $Q_{n}$ are commutative difference operators if and only if, given a constant $g$, we can find an $h$ such that the equations $\left(P_{m}-g I\right) \varphi=0,\left(Q_{n}-n I\right) \varphi=0$ have a common solution $Y(g, h)=0$.

Iroof

$$
\text { Let } P_{m}=\sum_{k=0}^{m} a_{k} \theta^{k}, Q_{n}=\sum_{k=0}^{n} b_{k} \theta^{k}
$$

where $a_{k}, b_{k}$ are constants or variables. Let $Y_{1}, Y_{2}, \ldots$ $Y_{m}$ be a linearly independent set of solutions of the basic difference equation

$$
\begin{equation*}
\left(P_{m}-g I\right) \varphi=0 \tag{2.27}
\end{equation*}
$$

We assume $P_{m}$ and $Q_{n}$ are commutative. Then

$$
\begin{equation*}
\left(P_{m}-g I\right) Q_{n} Y_{I}=Q_{n}\left(P_{m}-g I\right) Y_{I}=0 \tag{2.28}
\end{equation*}
$$

Thus $Q_{n} Y_{l}$ is a solution of the equation (2.27). Similarly the solutions $Q_{n} Y_{2}, Q_{n} Y_{3}, \ldots, Q_{n} Y_{m} c n$ be obtained. Then we have

$$
\begin{align*}
& Q_{n} Y_{1}=\alpha_{11} Y_{1}+\alpha_{12} Y_{2}+\ldots+\alpha_{1 m} Y_{m} \\
& Q_{n} Y_{2}=\alpha_{21} Y_{1}+\alpha_{22} Y_{2}+\ldots+\alpha_{2 m} Y_{m}  \tag{2.29}\\
& \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \omega_{m m} Y_{m} \\
& Q_{n} Y_{m}=\alpha_{m 1} Y_{1}+\alpha_{m 2} Y_{2}+\ldots \ldots+\alpha_{1}
\end{align*}
$$

Now let $Y=c_{1} Y_{1}+\mathrm{c}_{2} \mathrm{Y}_{2}+\ldots+\mathrm{c}_{\mathrm{m}} \mathrm{Y}_{\mathrm{m}}$

$$
\begin{equation*}
\text { Then } Q Y=h Y \text {. } \tag{2.30}
\end{equation*}
$$

provided that $h$ and the constants $c$ satisfy the equations $h c_{x}=\alpha_{r 1} c_{1}+\alpha_{r 2} c_{2}+\ldots+\alpha_{r m} c_{m}(r=1, \ldots, m)$. In order that these equations may be consistent it is necessary that $h$ be determined by the relation

$$
\left|\begin{array}{cccc}
\alpha_{11}-h & \alpha_{12} & \cdots & \alpha_{1 m} \\
\alpha_{21} & \alpha_{22-h} & \cdots & \alpha_{2 m} \\
\ldots & \ldots & & \ldots \\
\ldots & \ldots & & \cdots \\
\alpha_{m 1} & \alpha_{m 2} & & \alpha_{m m}-h
\end{array}\right|=0
$$

Thus corresponding to each $g$ there exist $m$ values of the constant $h$ such that the equation

$$
\begin{aligned}
& \left(P_{m}-g I\right) \varphi=0 \\
& \left(Q_{n}-h I\right) \varphi=0
\end{aligned}
$$

have a common solution.

Thus $\mathbf{Y}$ is a common solution of

$$
\begin{equation*}
\left(P_{m}-g I\right) \varphi=0 \text { and }\left(Q_{n}-h I\right) \varphi=0 . \tag{2.31}
\end{equation*}
$$

The constants g and h are therefore connected by some functional relation $Y(g, h)=0$.

The form of $Y(g, h)=0$ can be obtained directly from the eliminant of the basic difference equations

$$
\left(P_{m}-g I\right) \varphi=0,\left(Q_{n}-h I\right) \varphi=0
$$

Their common solution $Y$ will be more generally a comion solution of $m+n$ basic differonce equations

$$
\begin{aligned}
& \theta^{r}\left(P_{m}-g I\right) \varphi=0, r=0,1, \ldots, n-1 \\
& \theta^{s}\left(Q_{n}-h I\right) \varphi=0, s=0,1, \ldots, m-1 .
\end{aligned}
$$

Eliminating $\varphi, \theta \varphi, \theta^{2} \varphi, \ldots, \theta^{\mathrm{m}+\mathrm{n}-1} \varphi$ from the se $\mathrm{m}+\mathrm{n}$ equations, we get

$$
\begin{aligned}
& a_{0}(x)-g \quad a_{1}(x) \quad \ldots \quad a_{m}(x) 0 \quad 0 \quad . \quad 0 \\
& \begin{array}{lllll}
\theta a_{0}(x) & \left\{a_{0}(q x)-g+\theta a_{1}(x)\right\} & \ldots & \ldots & 0 \\
\theta^{2} a_{0}(x) & \left\{\left(\frac{2}{1}\right)_{q} q^{-1} \theta a_{0}(q x)+\theta^{2} a_{1}(x)\right\} & \ldots & \ldots & 0
\end{array} \\
& \theta^{n-1} a_{k}(x)\left\{\binom{n-1}{1} q^{2-n} \theta^{n-2} a_{o}(q x)+\theta^{n-1} a_{1}(x)\right\} \ldots \quad \ldots \\
& b_{0}(x)-h \quad b_{1}(x) \quad . b_{n}(x) \quad \ldots \quad 0 \\
& \theta b_{0}(x) \quad\left\{b_{0}(q x)-h+\theta b_{1}(x)\right\} \quad \ldots \quad . \quad 0 \\
& \theta^{2} b_{0}(x) \quad\left\{\left({\underset{l}{2}}_{2}^{q} q_{q}=1 b_{0}(q x)+\theta^{2} b_{l}(x)\right\}\right. \\
& \text {. } 0
\end{aligned}
$$

$$
\begin{align*}
& =0 \text {. } \tag{2.32}
\end{align*}
$$

This gives us $Y(g, h)=0$.
Hence if $P_{\text {rn }}$ and $Q_{n}$ are commutative given $g$, we get a common solution $Y$ such that $Y(g, h)=0$.

## Conversely

If for every $g$, we can find $h$ such that $\left(P_{m}-g I\right) \varphi=0,\left(Q_{n}-h I\right) \varphi=0$ have a common solution $Y(g, h)$, then $P_{m}$ and $Q_{n}$ are commutative operators. Proof

Operating on the common solution $Y$ with $P_{m} Q_{n}-Q_{n} P_{m}$, we get $\left(P_{m} Q_{n}-Q_{n} P_{m}\right) Y=P_{m} h Y-Q_{n} g Y$

$$
=\text { ghY - hgY }
$$

$$
=0 .
$$

Therefore $\left(P_{m} Q_{n}-Q_{n} P_{m}\right) \varphi=0$ has infinitely many solutions $Y(g, h)$, which we have seen, are linearly independent.

It is thus an identity and hence

$$
\begin{equation*}
P_{m} Q_{n}-Q_{n} P_{m}=0 \tag{2.33}
\end{equation*}
$$

Therefore $P_{m}$ and $Q_{n}$ are comrutative. Hence the result.

## Theorem 5

Any two operators $P_{m}$ and $Q_{n}$ are commutative if and only if they are connected by an algebraic identity $F\left(P_{n}, Q_{n 1}\right)=0$ with constant coefficients.

Proof (necessity)

Assume $P_{m}$ and $Q_{n}$ are commutative. Then
$Q_{n} P_{m}-P_{m} Q_{n}=0$, and hence
に. $A(x, \theta) F=0 \quad b y(2.11,2.12,2.13)$.

Also we get

$$
\left(P_{m}-g I\right) \varphi=0=\left(Q_{n}-h I\right) \varphi, \text { by (2.3I). }
$$

ie

$$
\begin{equation*}
F\left(P_{m}, Q_{n}\right) \varphi=F(g, h) \varphi=0, \text { by theorem (4) } \tag{2.34}
\end{equation*}
$$

Hence $Y$ is a solution of $F\left(P_{m}, Q_{n}\right) \varphi=0$.
Thus the basic difference equation

$$
\begin{equation*}
F\left(P_{m}, Q_{n}\right) \varphi=0 \tag{2.36}
\end{equation*}
$$

is satisfied by every $Y$. Since $g$ is arbitrary, there are infinitely many $Y$ 's and hence (2.36) is an identity unless the Y's are linearly dependent. Then

$$
F\left(P_{m}, Q_{n}\right)=0
$$

Now if Y's are linearly dependent we have

$$
\begin{equation*}
\alpha_{1} \mathrm{Y}_{1}+\alpha_{2} \mathrm{Y}_{2}+\ldots+\alpha_{\mathrm{s}} \mathrm{Y}_{\mathrm{s}}=0, \tag{2.37}
\end{equation*}
$$

where each $Y_{S}$ is a solution of $\left(P_{m}-g_{S} I\right) \varphi=0$ and the g's are all distinct. Here we take one solution each of every distinct equation $\left(P_{m}-g_{s} I\right) \varphi=0$; since the sum $\alpha_{1} Y_{1}+\alpha_{2} Y_{2}+\ldots \alpha_{s} Y_{s}$, of solutions of the same equation is itself a solution of the equation

$$
\begin{aligned}
P_{m}= & \sum_{k=0}^{m} a_{k}(x) \theta^{k}, \\
P_{m}^{2} f & =\sum_{k=0}^{m} a_{k}(x)\left[\sum_{j=0}^{m} \sum_{i=0}^{k}\binom{k}{i} q^{i(i-k)}\right. \\
& \left.\theta^{i} a_{j}\left(q^{k-i} x\right) \theta^{k+j-i}(f)\right] .
\end{aligned}
$$

Therefore
$P_{m}{ }^{2}=\sum_{k=0}^{m} a_{k}(x)\left[\sum_{j=0}^{m} \sum_{i=0}^{k}\binom{k}{i} q^{i(i-k)} \theta^{i} a_{j}\left(q^{k-i} x\right) \theta^{k \neq j-i}().\right]$ etc.

Operation with $P_{m}, P_{m}^{2}, \ldots, P_{m}^{s-l}$ on (2.37), gives $s-1$ relations

$$
\begin{gathered}
\alpha_{I} g_{I} Y_{I}+\alpha_{2} g_{2} Y_{2}+\ldots+\alpha_{S} g_{S} Y_{S} \\
\ldots \\
\alpha_{I} g_{I}{ }^{S-I_{Y}}{ }_{I}+\alpha_{2} g_{2}{ }^{s-I_{Y}} Y_{2}+\ldots
\end{gathered}
$$

Since no $\alpha_{S} Y_{S}$ is zero, the de'erminant

$$
\left|\begin{array}{llll}
g_{1} & g_{2} & \cdots & g_{s} \\
\cdot & \cdot & \cdots & \cdot \\
\cdot & \cdot & \cdots & \cdots \\
g_{1}^{s-1} & g_{2}^{s-1} & \cdots & g_{s}^{s-1}
\end{array}\right| \text { must vanish }
$$

But since all g's are distinct this is nc. zero. Hence $F\left(P_{m}, Q_{n}\right)=0$ identically by (2.36).

## Sufficiency

Proof
Suppose if possible $P_{m}$ and $Q_{n}$ are not commutative.
ie. $\quad Q_{n} P_{m}-P_{m} Q_{n} \neq 0$
ie. $A(x, \theta) F \quad \neq 0$, from (2.11), (2.12),(2.13)

This implies that there is no relationship between the coefficients of $P_{m}$ and $Q_{n}$. Hence there is no common solution $Y$ such that (2.34) is satisfied.

## Hence $F\left(P_{m}, Q_{n}\right) \neq 0$. Thus sufficiency is

established.

## Example

$$
\begin{aligned}
\text { Consider } P_{2} & =q x^{2} \theta^{2}+x \theta-I \\
Q_{3} & =q^{3} x^{3} \theta^{3}+q x^{2} \theta^{2}-(1+q) x \theta+(1+q) I
\end{aligned}
$$

Here it is seen that

$$
P_{2} Q_{3}=Q_{3} P_{2}
$$

ie. $P_{2}$ and $Q_{3}$ are commutative. Now we find $F(g, h)$ for these operators.

$$
\begin{aligned}
& \theta^{r}\left(P_{2}-g I\right) \varphi=0, \quad r=0,1,2 \\
& \theta^{s}\left(Q_{3}-h I\right) \varphi=0, \quad s=0,1
\end{aligned}
$$

ie.

$$
\begin{equation*}
q x^{2} \theta^{2} \varphi+x \theta \varphi-(l+g) \varphi=0 \tag{2.38}
\end{equation*}
$$

$$
\begin{align*}
& q^{3} x^{2} \theta^{3} \varphi+\left(2 q+q^{2}\right) x \theta^{2} \varphi-g \theta \varphi=0  \tag{2.39}\\
& q^{5} x^{2} \theta^{4} \varphi+\left(2 q^{2}+2 q^{3}+q^{4}\right) x \theta^{3} \varphi+\left(2 q+q^{2}-g\right) \theta^{2} \varphi=0  \tag{2.40}\\
& q^{3} x^{3} \theta^{3} \varphi+q x^{2} \theta^{2} \varphi-(1+q) x \theta \varphi+(1+q-h) \varphi=0  \tag{2.41}\\
& q^{6} x^{3} \theta^{4} \varphi+\left(2 q^{3}+q^{4}+q^{5}\right) x^{2} \theta^{3} \varphi-h \theta \varphi=0 \tag{2.42}
\end{align*}
$$

Eliminating $\theta^{4} \varphi, \theta^{3} \varphi, \theta^{2} \varphi, \theta \varphi, \varphi$ from (2.38), (2.39), (2.40), (2.41), (2.42), we get,

$$
\left|\begin{array}{ccccc}
0 & 0 & q x^{2} & x & -(1+g) \\
0 & q^{3} x^{2} & \left(2 q+q^{2}\right) x & -g & 0 \\
q^{5} x^{2} & \left(2 q^{2}+2 q^{3}+q^{4}\right) x & \left(2 q+q^{2}-g\right) & 0 & 0 \\
0 & q^{3} x^{3} & q x^{2} & -(1+q) x & (1+q-h) \\
q^{6} x^{3} & \left(2 q^{3}+q^{4}+q^{5}\right) x^{2} & 0 & -h & 0
\end{array}\right|=0
$$

ie. $g^{3}-\left(2 q+q^{2}\right) g^{2}-h^{2}-2(1+q) g h=0$.

Thus $\quad F(g, h)=g^{3}-\left(2 q+q^{2}\right) g^{2}-h^{2}-2(1+q) g h=0$. Thus $F\left(P_{2}, Q_{3}\right)=P_{2}{ }^{3}-\left(2 q+q^{2}\right) P_{2}{ }^{2}-Q_{3}{ }^{2}-2(1+q) P_{2} Q_{3}=0$.

Thus we have verified the the orem for this example.

## cHAPTER III

SOME SPECIAL BASIC COMMUTATIVE DIFFERENCE OPERATORS AND SOLUTION OF BASIC DIFFERENCE EQUAIIONS

In this chapter we define some special basic commutative difference operators $P_{m}$ and $Q_{n}$ of order $m$ and $n$ respectively. We obtain new operators $P_{m}$ ' and $Q_{n}{ }^{\prime}$ by transference of the common factors of $P_{m}$ and $Q_{n}$ respectively and show that the characteristic relations $F\left(P_{m}, Q_{n}\right)$ and $F\left(P_{m}^{\prime}, Q_{n}^{\prime}\right)$ are primarily the same. Taking polynomial operators $f(\delta)$ in terms of $\delta=x \Theta$, we obtain their inverse $f$ ). We prove some related theorems and hence solve some basic difference equations.

1. SPECIAL BASIC COMMUTATIVE DIFFERENCE OPERATORS

Let $\quad P_{m}=\theta^{m}=q^{\frac{-m(m-1)}{2}} x^{-m}{\underset{k=0}{m-1}(\delta-[k] I), ~}_{m=0}^{m}(\delta)$

where $\delta=x \theta$ and $[k]=\frac{1-q}{1-q}$.

Lemma $P_{m} Q_{n}=Q_{n} P_{m}=e^{m+n}$

Proof
Let the lemma be true for $Q_{r} P_{m}$.
Hence $\quad Q_{r} P_{m} f=q^{-\left(\frac{m+r)}{2}(m+r-1)\right.} x^{-(m+r)} \underset{\substack{m+r-1}}{\substack{m \\ m}}(\delta-[k] I) f$

$$
=\theta^{m+r_{f}}
$$

Now

$$
\begin{aligned}
& Q_{r+1} P_{m} f=\theta \theta^{m+r_{f}} \\
& =q^{-\frac{(m+r)(m+r-1)}{2}} \theta\left[x^{-(m+r)} \underset{k=0}{m+r-1}(\delta-[k] I) f\right] \\
& =q^{-\left(\frac{m+r)(m+r-1)}{2}\right.}\left[q^{-(m+r)} x^{-(m+r)} \underset{\substack{\pi^{\prime}=0}}{m+r-1}(\delta-[k] I) f\right. \\
& \left.-[m+r] q^{-(m+r)} x^{-\left(m+r+l^{\prime}\right)} \underset{k=0}{m+r-1}(\delta-[k] I) f\right] \\
& =q^{-\frac{(m+r)(m+r-1)}{2}} q^{-(m+r)}\left[x^{-(m+r+1)} \delta \underset{k=0}{m+r-1}(\delta-[k] I \neq f\right. \\
& \left.-[m+r] x^{-(m+r+1)} \underset{k=0}{m+r-1}(\delta-[k] I) f\right] \\
& =q^{-\left(\frac{m+r)(m+r+1)}{2}\right.} \underset{x}{-(m+r+1)} \underset{k=0}{m+r-1}(\delta-[k])(\delta-[m+r]) f
\end{aligned}
$$

$$
\begin{aligned}
& =q^{-\left(\frac{m+r)(m+r+\overline{1})}{2}\right.} x^{-(m+r+1)} \underset{\substack{m+r \\
k=0}}{m}(\delta-[k] I) f \\
& =\theta^{m+r+1} f .
\end{aligned}
$$

Hence if the lemma is true for $Q_{r} P_{m}$ it is true for $Q_{r+1} P_{m}$.

Now $Q_{1} P_{m}=\theta \theta^{m_{f}}=\theta\left[q^{\frac{-m(m-1)}{2}} x^{-m}{\underset{k=0}{\pi}(\delta-[k] I)] f}^{m}\right.$

$$
=q^{\frac{-m(m-1)}{2}} \theta\left[x^{-m} \prod_{k=0}^{m-1}(\delta-[k] I) f\right.
$$

$$
=q^{-\frac{m(m-1)}{2}}\left[q^{-m-m} \theta \prod_{k=0}^{m-1}(\delta-[k] I) f\right.
$$

$$
\left.-[m] q^{-m} x^{-(m+1)} \operatorname{m}_{k=0}^{m-1}(\delta-[k] I) f\right]
$$

$$
=q^{\frac{-m(m-1)}{2}} q^{-m}\left[x^{-(m+1)} \delta \prod_{k=0}^{m-1}(\delta-[k] I) f\right.
$$

$$
\left.-[m] x^{-(m+1)} \prod_{k=0}^{m-1}(\delta-[k] I) f\right]
$$

$$
=q^{-\frac{m(m+1)}{2}} x^{-(m+1)}{\underset{k=0}{m-1}(\delta-[k][x)(\delta-[m] I) f}^{m}
$$

$$
\begin{aligned}
& =q^{-\frac{m(m+1)}{2}} x^{-(m+1)}{\underset{k=0}{m}(\delta-[k] I\rangle f}^{=\theta^{m+1} f .}
\end{aligned}
$$

Hence the lemma is true for all $n$
ie. $\quad Q_{n} P_{m}=\theta^{m+n}$ is true for all $m$ and $n$.

Similarly we can prove that

$$
P_{m} Q_{n}=\theta^{m+n} \text { for all } m \text { and } n
$$

Hence the result,

Also

$$
\begin{aligned}
\theta \theta^{2} f & =x^{-1} \delta q^{-1}{ }_{Y}^{-2} \delta(\delta-1) f \\
& =x^{-1} x \theta q^{-1} x^{-2} x \theta(x \theta f-f) \\
& =\theta q^{-1} x^{-1}\left[q x \theta^{2} f+\theta f-\theta f\right] \\
& =\theta \theta^{2} f \\
& =\theta^{3} f
\end{aligned}
$$

The result follows by induction.

## Characteristic identity of $P_{m}$ and $Q_{n}$

We have $\quad P_{m}=\theta^{m}, Q_{n}=\theta^{n}$.

Consider the basic difference equations

$$
\begin{aligned}
& \theta^{r}\left(P_{m}-g I\right) f=0, r=0,1, \ldots, n-1 \\
& \theta^{s}\left(Q_{n}-h I\right) f=0, s=0,1, \ldots, m-1 .
\end{aligned}
$$

Hence

$$
\begin{align*}
& \theta^{m}-g f=0 \\
& \theta^{m+l_{f-g \theta f}}=0 \\
& \text {...................... } \\
& \theta^{m+n-1} f-g \theta^{n-1} f=0 \\
& \theta^{n_{f}}-h f=0  \tag{3.3}\\
& \theta^{n+l_{f}}-h \theta f=0 \\
& \theta^{m+n-1}-h \theta^{m-1} f=0
\end{align*}
$$

Eliminating $f, \theta f, \theta^{2} f \ldots \theta^{m+n-l_{f}}$ from equations (3.3) we get that the determinant

Expanding we get

|  | $g^{n}-h^{m}$ | $=0$. |
| :--- | :--- | :--- |
| ie. | $F(g, h)$ | $=g^{n}-h^{m}$. |
| Therefore $\quad F\left(P_{m}, Q_{n}\right)$ | $=P_{m}^{n}-Q_{n}^{m}$, by (2.34) |  |

2. DERIVATION OF NEW OPERATORS BY TRANSFERENCE OF COMTION FACTORS

$$
\begin{aligned}
& P_{m}=\theta^{m}=q^{-\frac{m(m-1)}{2}} \times \sum_{k=0}^{m-1}(\delta-[k]) \\
& Q_{n}=\theta^{n}=q^{\frac{-n(n-1)}{2}-n} \sum_{k=0}^{n-1}(\delta-[k] I)
\end{aligned}
$$

Let m < n.

Then we see that the operators $\delta,(\delta-1),(\delta-[2]), \ldots$, $(\delta-[\mathrm{m}-1])$ are common for both.

Hence we can transfer any one cf these operators to the left end of $P_{m}$ and $Q_{n}$. This transformation leads us to new operators. Hence given a pair $P_{m}, Q_{n}$; we get $m$ pair of new operators. Let them be $P_{m}{ }^{\prime}, Q_{n}{ }^{\prime} ; P_{m}{ }^{2}, Q_{n}{ }^{2}$, $\ldots, P_{m}{ }^{m}, Q_{n}{ }^{m}$.

Now we transfer $\delta$ to the left and find $P_{m}{ }^{\prime}, Q_{n}{ }^{\prime}$.

$$
P_{m}=q^{-\frac{m(m-1)}{2}} x^{-m} \delta(\delta-1)(\delta-[2] I) \ldots(\delta-[m-1] I)
$$

## Therefore

$$
\begin{aligned}
& P_{m}^{\prime} \quad=\quad q^{-\frac{m(m-1)}{2}} \delta x^{-m}(\delta-1)(\delta-[2] I) \ldots(\delta-[m-1] I) \\
& =q^{\frac{-m(m-1)}{2}} x \theta x^{-m}(\delta-1)(\delta-[2] I) \ldots(\delta-[m-1] I) \\
& P_{m}^{\prime} f=q^{-\frac{m(m-1)}{2}} x \Theta\left[x^{-m} \prod_{k=1}^{m-1}(\delta-[k] I)\right] f \\
& =q^{-\frac{m(m-1)}{2}} \times\left[q^{-m} x^{-m} \Theta \prod_{k=1}^{m-1}(\delta-[k] I) f\right. \\
& -[m] q^{-m} x^{-(m+1)}{\underset{k=1}{m-1}(\delta-[k] I) f]}^{m} \\
& =q^{\frac{-m(m-1)}{2}} q^{-m} x^{-m} \prod_{k=1}^{m-1}(\delta-[k] \text { }:(\delta-[m] I) f \\
& =q^{\frac{-m(m+1)}{2}} x^{-m} \underset{k=1}{m}(\delta-[k] I) f .
\end{aligned}
$$

Hence
$P_{m}^{\prime}=q^{-\frac{m(m+1)}{2}} x^{-m}{\underset{k=1}{m}(\delta-[k] \dot{x})}_{m}^{m}$
$Q_{n}^{\prime}=q^{\frac{-n(n+1)}{2}} x^{-n} \prod_{k=1}^{n}(\delta-[k] I)$.

The other pairs also can be obtained similarly.

## Now we find the characteristic identity of $P_{m}{ }^{\prime} Q_{n}^{\prime}$ '

Consider the basic difference equations

$$
\begin{aligned}
& \theta^{r}\left(P_{m}^{\prime}-g^{\prime} I\right) f=0, r=0,1, \ldots, n-1 \\
& \theta^{s}\left(Q_{n}^{\prime}-h ' I\right) f=0, s=0,1, \ldots, m-1 .
\end{aligned}
$$

Pliminating $f, \theta f, \ldots, \theta^{m+n-l_{f}}$ from these $m+n$ basic difference equations, we get the same form as (3.4).

Hence $F^{\prime}\left(g^{\prime}, h^{\prime}\right)=g^{\prime n}-h^{\prime m}$.
Therefore $F\left(P_{m}, Q_{n}\right)=F\left(P_{m}, Q_{n}{ }^{\prime}\right)$
Similarly $F\left(P_{m}{ }^{\prime}, Q_{n}{ }^{\prime}\right)=F\left(P_{m} \prime, Q_{n} \prime\right)$....

$$
\begin{aligned}
& =F\left(P_{m}^{m}, Q_{n}^{m}\right)=F\left(P_{m}, Q_{n}\right) \\
& =P_{m}^{n}-Q_{n}^{m} .
\end{aligned}
$$

Hence a set of basic difference equations is generated by the same characteristic identity.

## Example

$$
\text { Let } m=2, n=3
$$

$$
P_{2}=\theta^{2}, Q_{3}=\theta^{3}
$$

Hence

$$
\begin{align*}
& \theta^{r}\left(P_{2}-g I\right) f=0, r=0,1,2 \\
& \theta^{s}\left(Q_{3}-h I\right) f=0, s=0,1 \text { give } \\
& \theta^{3} f-g f=0  \tag{3.5}\\
& \theta^{3} f-g \theta f=0  \tag{3.6}\\
& \theta^{4} f-g \theta^{2} f=0  \tag{3.7}\\
& \theta^{3} f-h f=0  \tag{3.8}\\
& \theta^{4} f-h \theta f=0 \tag{3.9}
\end{align*}
$$

Eliminating $f, \theta f, \theta^{2} f, \theta^{3} f, \theta^{4} f$ from (3.5), (3.6), (3.7), (3.8), (3.9) we have

$$
\left|\begin{array}{ccccc}
-g & 0 & 1 & 0 & 0 \\
0 & -g & 0 & 1 & 0 \\
0 & 0 & -g & 0 & 1 \\
-h & 0 & 0 & 1 & 0 \\
0 & -h & 0 & 0 & 1
\end{array}\right|=0
$$

ie

$$
\begin{equation*}
g^{3}-h^{2}=0 \tag{3.10}
\end{equation*}
$$

Now

$$
\begin{aligned}
& P_{2}=\theta^{2}=q^{-1} x^{-2} \delta(\delta-1) \\
& Q_{3}=\theta^{3}=q^{-3} x^{-3} \delta(\delta-1)(\delta-[2])
\end{aligned}
$$

Transferring $\delta-1$, we get

$$
\begin{aligned}
P_{2}^{\prime} & =q^{-1}(\delta-1) x^{-2} \delta=q^{-2} \theta^{2}-\left(q^{-2}+q^{-1}\right) x^{-1} \theta \\
Q_{3}^{\prime} & =q^{-3}(\delta-1) x^{-3} \delta(\delta-[2]) \\
& =q^{-3} \theta^{3}-\left(q^{-2}+q^{-3}+q^{-4}\right) x^{-1} \theta^{2}+\left(q^{-2}+q^{-3}+q^{-4}\right) x^{-2} \theta
\end{aligned}
$$

Now $\quad \theta^{r}\left(P_{2}^{\prime}-g^{\prime} I\right) f=0, \quad r=0,1,2$

$$
\theta^{s}\left(Q_{3}^{\prime}-h ' I\right) f=0, \quad s=0,1
$$

give $\quad q^{-2} \theta^{2} f-\left(q^{-2}+q^{-1}\right) x^{-1} \theta f-g^{\prime} f=0$

$$
\begin{align*}
& q^{-2} \theta^{3} f-\left(q^{-2}+q^{-3}\right) x^{-1} \theta^{2} f+\left\{\left(q^{-2}+q^{-3}\right) x^{-2}-g^{1}\right\} \theta f=0(3.12)  \tag{3.11}\\
& q^{-2} \theta^{4} f-\left(q^{-3}+q^{-4}\right) x^{-1} \theta^{3} f+\left\{\left(q^{-3}+q^{-4}\right) x^{-3}\right.
\end{align*}
$$

$$
\begin{equation*}
\left.\therefore\left(q^{-4}+q^{-5}\right) x^{-2}-g^{1}\right\} \theta^{2} f-\left(q^{-3}+2 q^{-4}+q^{-5}\right) x^{-3} \theta f=0 \tag{3.13}
\end{equation*}
$$

$$
q^{-3} \theta^{3} f-\left(q^{-2}+q^{-3}+q^{-4}\right) x^{-1} \theta^{2} f
$$

$$
\begin{equation*}
+\left(q^{-2}+q^{-3}+q^{-4}\right) x^{-2} \theta f-h^{\prime} f=0 \tag{3.14}
\end{equation*}
$$

$$
q^{-3} \theta^{4} f-\left(q^{-3}+q^{-4}+q^{-5}\right) x^{-1} \theta^{3} f
$$

$$
+\left(q^{-3}+2 q^{-4}+2 q^{-5}+q^{-6}\right) x^{-2} \theta^{2} f
$$

$$
\begin{equation*}
-\left(q^{-4}+2 q^{-5}+2 q^{-6}+q^{-7}\right) x^{-3} \theta f-h^{\prime} \theta f=0 \tag{3.15}
\end{equation*}
$$

Eliminating $f, \theta f, \theta^{2} f, \theta^{3} f, \theta^{4} f$ from (3.11), (3.12), (3.13), (3.14), (3.15) we get that the determinant
vanishes.

Expanding this determinant we get

Hence

$$
\begin{aligned}
& g^{1^{3}}-h^{\prime 2}=0 \\
& F\left(P_{2}^{\prime}, Q_{3}^{\prime}\right)=F\left(P_{2}, Q_{3}\right) \text { from (3.10). }
\end{aligned}
$$

3. POLYNOMIAL OPERATORS AND THE INVERSE OPERATOR

We see that

$$
\delta=x \theta, \delta^{2}=\delta \delta=(x \theta)(x \theta)
$$

Therefore,

$$
\delta^{2} \neq x^{2} \theta^{2}, x^{n} \theta^{n} \neq \delta^{n}
$$

Now we consider the polynomial operator

$$
f(\delta)=\sum_{k=0}^{m} a_{k} \delta^{k}, a_{k} \text { constants }
$$

Theorem 1

$$
\begin{align*}
f(\delta) x^{a} & =f([a]) x^{a} \text { for every } a  \tag{3.16}\\
\delta x^{a} & =x \theta x^{a} \\
& =x[a] x^{a-1} \\
& =[a] x^{a} . \tag{3.17}
\end{align*}
$$

We assume $\delta^{m_{x}}{ }^{\mathrm{a}}=[\mathrm{a}]^{\mathrm{m}_{\mathrm{x}}}{ }^{\mathrm{a}}$.
Therefore $\delta^{m+1} x^{a}=\delta\left[[a]^{m} x^{a}\right]$

$$
\begin{align*}
& =[a]^{m} x \theta x^{a} \\
& =[a]^{m+1} x^{a} \tag{3.18}
\end{align*}
$$

$B_{i}$ induction the result is true for all m . Therefore.

$$
\begin{aligned}
f(\delta) x^{a}= & {\left[a_{0} I+a_{1} \delta+a_{2} \delta^{2}+\ldots+a_{m} \delta^{m}\right] x^{a} } \\
= & a_{0} x^{a}+a_{1}[a] x^{a}+\ldots+a_{m}[a]^{m} x^{a}, \\
& \text { from }(3.17) \text { and }(3.18) \\
= & {\left[a_{0} I+a_{1}[a]+a_{2}[a]^{2}+\ldots+a_{m}[a]^{m}\right] x^{a} } \\
= & f([a]) x^{a} . \text { Hence the result. }
\end{aligned}
$$

## Theorem 2

$$
\begin{equation*}
f\left(\delta^{-1}\right) x^{a}=f(1 /[a]) x^{a}, \quad a>0 . \tag{3.19}
\end{equation*}
$$

Proof

$$
\begin{aligned}
\delta^{-1} x^{a} & =\theta^{-1} x^{-1} x^{a} \\
& =\theta^{-1} x^{a-1} \\
& =S x^{a-1}(q, x) \\
& =(1-q) x \sum_{k=0}^{\infty} q^{k}\left(q^{k} x\right)^{a-1} \text { by }(1.20) \\
& =(1-q) x^{a} \sum_{k=0}^{\infty}\left(q^{a}\right)^{k}
\end{aligned}
$$

Hence $\quad \delta^{-1} x^{a}=\frac{(1-q) x^{a}}{1-q^{a}}$

$$
\begin{equation*}
=\frac{x^{a}}{[a]} \tag{3.20}
\end{equation*}
$$

Assume $\delta^{-n} x^{a}=\frac{x^{a}}{[a]^{n}}$.
Therefore $\delta^{-(n+1)} x^{a}=\delta^{-1}\left(\delta^{-n} x^{a}\right)$

$$
\begin{aligned}
& =\delta^{-1}\left(x^{a} /\left([a]^{n}\right)\right) \\
& =1 /\left([a]^{n}\right) \theta^{-1} x^{-1} x^{a} \\
& =1 /\left([a]^{n}\right) \theta^{-1} x^{a-1}
\end{aligned}
$$

$$
\begin{align*}
& =1 /\left([a]^{n}\right)\left(x^{a} /([a])\right) \\
& =x^{a} /\left([a]^{n+1}\right) \tag{3.21}
\end{align*}
$$

By induction, we get the result. Therefore if

$$
\begin{aligned}
f\left(\delta^{-1}\right)= & \left(a_{0} I+a_{1} \delta^{-1}+\ldots+a_{n} \delta^{-n}\right) \\
f\left(\delta^{-1}\right) x^{a}= & \left(a_{0} I+a_{1} \delta^{-1}+a_{2} \delta^{-2}+\ldots+a_{n} \delta^{-n}\right) x^{a} \\
= & \left\{\left(a_{0} I+a_{1}(1 . /[a])+a_{2}\left(1 /[a]^{2}\right)+\ldots\right.\right. \\
& \left.+a_{n}\left(1 /[a]^{n}\right)\right\} x^{a} \\
= & f(1 /[a]) x^{a} \text { from (3.20) and (3.21) }
\end{aligned}
$$

## Theorem 3

$$
f(\delta)\left(x^{a} y\right)=x^{a} f\left(q^{a} \delta+[a]\right) y
$$

## Proof

$$
\begin{aligned}
\delta\left(x^{a} y\right) & =x \theta\left(x^{a} y\right) \\
& =x\left[q^{a} x^{a} \Theta y+[a] x^{a-1} y\right] \\
& =x^{a}\left[q^{a} \delta+[a]\right] y \\
\cdot \cdot \cdot \cdot \cdot & \cdot \cdot \cdot \cdot \cdot \cdot \cdot \cdot \cdot \cdot \cdot \cdot \\
\delta^{n}\left(x^{a} y\right) & =x^{a}\left[q^{a} \delta+[a]\right]^{n} y
\end{aligned}
$$

$\left[q^{a} \delta+[a]\right]^{n}$ means $\left[q^{a} \delta+[a]\right]\left[q^{a} \delta+[a]\right] \ldots$ operating $n$ times on $y$. Therefore

$$
\begin{aligned}
f(\delta)\left(x^{a} y\right)= & {\left[a_{0} I+a_{1} \delta+a_{2} \delta^{2}+\ldots+a_{n} \delta^{n}\right]\left(x^{a} y\right) } \\
= & \left\{a_{0} x^{a}+a_{1} x^{a}\left[q^{a^{2}} \delta+[a]\right]+a_{2} x^{a}\left[q^{a} \delta+[a]\right]^{2}\right. \\
& \left.+\ldots+a_{n} x^{a}\left[q^{a^{2}} \delta+[a]\right]^{n}\right\} y \\
= & x^{a_{f}}\left(q^{a} \delta+[a]\right) y .
\end{aligned}
$$

Hence the result.

## Theorem 4

If $f_{1}, f_{2}, \ldots, f_{n}$ are polynomials with constant coefficients, then

$$
\begin{align*}
& x^{a} n_{f_{n}}(\delta) x^{a}{ }^{a}-l_{f_{n-1}}(\delta) \ldots x^{a}{ }^{2} f_{2}(\delta) x^{a} 1_{f_{1}}(\delta) \\
& =x^{a_{1}+a_{2}+\ldots+a_{n_{f_{1}}}(\delta) f_{2}\left(q^{a_{1}}{ }_{\left.\delta+\left[a_{1}\right]\right)}\right), ~} \\
& f_{3}\left(q^{\hat{a}_{2}+a_{1}}{ }_{\left.\delta+\left[a_{1}+a_{2}\right]\right)} \ldots \ldots \cdot\right. \\
& f_{n}\left(q^{a_{1}+a_{2}+\ldots+a_{n-1}} \delta+\left[a_{1}+a_{2}+\ldots+a_{n-1}\right]\right) \tag{3.22}
\end{align*}
$$

## Proof

In theorem 3 we have proved that
$f(\delta)\left(x^{a} y\right)=x^{a} f\left(q^{a} \delta+[a]\right) y$

Now we apply this result from right to left on the left side of the required equality. Therefore

$$
\begin{aligned}
& x^{a^{a} n_{f_{n}}(\delta)} x^{a}{ }^{a}-1_{f_{n-1}}(\delta) x^{a}{ }^{n-2} f_{f_{n-2}}(\delta) \ldots x^{a} 2_{f_{2}}(\delta) x^{a_{1}} f_{f_{1}}(\delta) \\
& =x^{a} n_{f_{n}}(\delta) x^{a}{ }^{a} l_{1_{n-1}}(\delta) x^{a}{ }^{a} 2_{f_{n-2}}(\delta) \ldots x^{a_{1}+a_{2}} f_{1}(\delta) f_{2}\left(q^{a_{1}}{ }_{\left.\delta+\left[a_{1}\right]\right)}\right. \\
& =x^{a^{n}} f_{n}(\delta) x^{a_{n-1}} f_{f_{n-1}}(\delta) \ldots x^{a_{1}+a_{2}+a_{3_{f_{1}}}(\delta) f_{2}\left(q^{a_{1}} \delta+\left[a_{1}\right]\right)} \\
& f_{3}\left(q^{a_{1}+a_{2}} \delta+\left[a_{1}+a_{2}\right]\right) \\
& =x^{a_{1}+a_{2}+a_{3}+\ldots+a_{n_{1}}(\delta) f_{2}\left(q^{a_{1}}{ }_{\left.\delta+\left[a_{1}\right]\right) f_{3}\left(q^{a_{1}+a_{2}}\right.}{ }^{+}\left[a_{1}+a_{2}\right]\right)} \\
& f_{n}\left(q^{a_{1}+a_{2}+\ldots+a_{n-1}} \delta+\left[a_{1}+a_{2}+\ldots+a_{n-1}\right]\right)
\end{aligned}
$$

Hence the result.

## Corollary (1)

$$
\text { Put } \begin{align*}
a_{r}= & a, r=1,2, \ldots, n \\
f_{r}(\delta)= & f(\delta) \text { then }(3.22) \text { reduces to } \\
{\left[x^{a} f(\delta)\right]^{n}=} & x^{n a_{f}(\delta)} f\left(q^{a} \delta+[a]\right) \ldots \ldots . . \\
& f\left(q^{\left.(n-1) a_{\delta}+[(n-1)]\right)}\right. \tag{3.23}
\end{align*}
$$

## Corollary (2)

$$
\text { Put } a=-1 \text { and } f(\delta)=\delta \text { in (3.23) }
$$

Then (3.23) reduces to

$$
\begin{aligned}
\left(x^{-1} \delta\right)^{n}= & x^{-n} \delta\left(q^{-1} \delta+[-1]\right)\left(q^{-2} \delta+[-2] \ldots\right. \\
& \left(q^{-(n-1)} \delta+[-n(n-1)]\right) \\
= & x^{-n} q^{\frac{-n(n-1)}{2}} \delta(\delta-1) \ldots(\delta-[n-1])
\end{aligned}
$$

Since

$$
\begin{aligned}
q^{-1} \delta+[-1] & =q^{-1}(\delta-1) \\
q^{-2} \delta+[-2] & =q^{-2} \delta-q^{-2}[2] \\
& =q^{-2}(\delta-[2]) \text { and so on. }
\end{aligned}
$$

We see that

$$
x^{-1} \delta=x^{-1} x \theta=0
$$

Therefore (3.24) reduces to

$$
\begin{aligned}
\theta^{n} & =q^{\frac{-n(n-1)}{2}} x^{-n} \delta(\delta-1) \ldots(\delta-[n-1] I) \\
& =q^{\frac{-n(n-1)}{2}} x^{-n}{\underset{k=0}{n-1}(\delta-[k] I)}^{n}{ }^{n} \quad
\end{aligned}
$$

This is the same as (3.1) and (3.2). Hence by using theoreir (4) we can form basic commutative difference operators easily.

A commutative triad

$$
\begin{aligned}
& P_{3}=q^{-6} x^{-3} \delta(\delta-1)(\delta-[5] I) \\
& Q_{4}=q^{-10} x^{-4} \delta(\delta-1)(\delta-[3] I)(\delta-[6] I) \\
& R_{5}=q^{-5} x^{-5} \delta(\delta-1)(\delta-[3] I)(\delta-[4] I)(\delta-[7] I)
\end{aligned}
$$

We find that $P_{3}, Q_{4}, R_{5}$ form a commatative triad.

Also

$$
\begin{aligned}
& P_{5}^{4}=Q_{4}^{3} \\
& Q_{4}^{5}=R_{5}^{4} \\
& R_{5}^{3}=P_{3}^{5} \\
& P_{3} R_{5}=Q_{4}^{2} \\
& Q_{4} R_{5}=P_{3}^{3}
\end{aligned}
$$

## Example

$$
\begin{aligned}
& \text { Let } \begin{aligned}
P & =q^{-3} x^{-2} \delta(\delta-[3]) \\
\text { Then } & =q^{-6} x^{-3} \delta(\delta-[2])(\delta-[4]) \\
& =q^{-3} x^{-2} \delta(\delta-[3]) q^{-6} x^{-3} \delta(\delta-[2])(\delta-[4]) \\
\text { Now }\left(q^{-3} \delta-[3]+[-3]\right) & =x^{-3}\left(q^{-3} \delta-[3]+[-3]\right) \delta(\delta-[2])(\delta-[4]) \\
& =q^{-3} \delta-\left(\frac{1-q^{3}}{1-q}\right)-q^{-3}\left(\frac{1-q^{3}}{1-q}\right) \\
& =q^{-3} \delta-\left(\frac{1-q 3}{1-q}\right)\left(1+q^{-3}\right) \\
& =q^{-3}(\delta-[6])
\end{aligned}
\end{aligned}
$$

## Therefore

$$
\begin{aligned}
P Q & =q^{-9} x^{-5}\left(q^{-3} \delta+[-3]\right) q^{-3}(\delta-[6]) \delta(\delta-[2])(\delta-[4]) \\
& =q^{-9} x^{-5} q^{-3}(\delta-[3])(\delta-[6]) \delta(\delta-[2])(\delta-[4]) \\
& =q^{15} x^{-5} \delta(\delta-[2])(\delta-[3])(\delta-[4])(\delta-[6]) \\
& =Q P
\end{aligned}
$$

## Also we see that

$$
\begin{aligned}
P^{3} & =q^{-21} x^{-6} \delta(\delta-[2])(\delta-[3])(\delta-[4])(\delta-[5])(\delta-[7]) \\
& =Q^{2}
\end{aligned}
$$

4. SOLUTION OF BASIC DIfference equifions
a) Consider the difference equation

$$
\theta^{m_{f}}=0
$$




Let $\sum_{k=0}^{m-1} f_{k}(x)$ be the solution of $\oplus^{m} f=0$

Therefore

$$
(\delta-[k]) f_{k}(x) \quad=0
$$

ie. $\quad x \otimes f_{k}(x) \quad=\left(\frac{1-q^{k}}{1-q}\right) f_{k}(x)$
ie. $\quad x\left[\frac{f_{k}(x)-f_{k}(q x)}{(l-q) x}\right]=\left(\frac{1-q^{k}}{1-q}\right) f_{k}(x)$
or

$$
f_{k}(x)-f_{k}(q x) \quad=\left(1-q^{k}\right) f_{k}(x)
$$

or
$f_{k}(q x)$
$=\left\{1-\left(1-q^{k}\right)\right\} f_{k}(x)$
or

$$
f_{k}(q x)
$$

$$
=q^{k} f_{k}(x)
$$

Hence $f_{k}(x)$

$$
=c_{k} x^{k}
$$

Hence in this case polynomial solutions are possible unto any degree.
b) Consider $(\delta-\lambda x) f(x)=0$
ie

$$
f(x)-f(q x)-(1-q) \lambda x f(x)=0
$$

or

$$
\{1-(1-q) x \lambda f(x)=f(q x)
$$

$$
\begin{aligned}
& \text { Therefore } \begin{aligned}
f(x) & =\frac{f(q x)}{\{1 \cdots x(1-q) \lambda\}} \\
\text { or } f(x) & =\frac{c}{\substack{\infty \\
r=0}}\left[1-x(1-q)^{-1} \lambda q^{n}\right]
\end{aligned} \\
&=e_{q}\{(1-q) \lambda x\}
\end{aligned}
$$

converges for all x since $\mathrm{o}<\mathrm{q}<1$.
c) Consider the basic difference equation

$$
q x^{2} \theta^{2} f(x)+x \theta f(x)-f(x)=x^{3}
$$

Now by (3.1)

$$
\begin{aligned}
q x^{2} \theta^{2} & =q x^{2} q^{-1} x^{-2} \delta(\delta-I) \\
& =\delta^{2}-\delta
\end{aligned}
$$

So we have $\left(\delta^{2}-I\right) f(x)=x^{3}$
Therefore $f(x)=\left(\delta^{2}-1\right)^{-1} x^{3}$

$$
=\frac{x^{3}}{[3]^{2}-1} \text { by (3.16) }
$$

Hence $\quad f(x) \quad=\frac{x^{3}}{\left(1+q+\dot{q}^{2}\right)^{2}-1}$
d) Consider the basic difference equation

$$
q \theta^{2} f(x)=\left(q x^{2} \theta^{2}+x \theta-m^{2}\right) f(x)
$$

Nultiplying both sides by $\mathrm{x}^{2}$ we have
or

$$
\begin{align*}
& q x^{2} \theta^{2} f=x^{2}\left(q x^{2} \theta^{2}+x \theta-m^{2}\right) f \\
& \delta(\delta-1) f=x^{2}\left\{\delta(\delta-1)+\delta-m^{2}\right\} f \\
& \delta(\delta-1) f=x^{2}\left(\delta^{2}-m^{2}\right) f \tag{3.25}
\end{align*}
$$

or
Let $f=f_{0}+f_{1}+f_{2}+\ldots$ be a solution. Then (3.25) gives

$$
\begin{align*}
& \delta(\delta-1) f_{0}=0  \tag{3.26}\\
& \delta(\delta-1) f_{1}=x^{2}\left(\delta^{2}-m^{2}\right) f_{0}  \tag{3.27}\\
& \delta(\delta-1) f_{2}=x^{2}\left(\delta^{2}-m^{2}\right) f_{1}  \tag{3.28}\\
& \cdots \cdots \cdots \cdots
\end{align*}
$$

Now we solve $\delta(\delta-1) f_{0}=0$ by the power series metmod and consider the particular case

$$
f_{0} \quad=1 \text { or } x \text { (say) }
$$

We substitute $f_{0} \quad=x$ in (3.27)
ie. $\quad \delta(\delta-1) f_{I}=x^{2}\left(\delta^{2}-m^{2}\right) x$
$=x^{3}\left(1-m^{2}\right)$ by (3.16)
$=\left(1-m^{2}\right) x^{3}$
Therefore

$$
\begin{align*}
f_{1} \quad & =\delta^{-1}(\delta-1)^{-1}\left(1-m^{2}\right) x^{3} \\
& =\left(1-m^{2}\right) \delta^{-1}(\delta-1)^{-1} x^{3} \\
& =\frac{\left(1-m^{2}\right) x^{3}}{[3][2]} \text { by }(3.16) \tag{3.29}
\end{align*}
$$

Substituting (3.29) in (3.28) we have

$$
\begin{aligned}
\delta(\delta-1) f_{2} & =\frac{x^{2}\left(\delta^{2}-m^{2}\right)\left(1 \cdots m^{2}\right) x^{3}}{[3][2]} \\
& =\frac{x^{5}\left([3]^{2}-m^{2}\right)\left(1-m^{2}\right)}{[3][2]} \text { by }(3.16) \\
& =\frac{\left(1-m^{2}\right)\left([3]^{2}-m^{2}\right) x^{5}}{[3][2]} \\
f_{2} & =\frac{\left(1-m^{2}\right)\left([3]^{2}-m^{2}\right)}{[3][2]} \delta^{-1}(\delta-1)^{-1} x^{5}
\end{aligned}
$$

Therefore

$$
=\frac{\left(1-\mathrm{m}^{2}\right)\left([3]^{2}-\mathrm{m}^{2}\right) \mathrm{x}^{5}}{[2][3][4][5]} \text { by }(3.16)
$$

And so on

$$
f_{r}=\frac{\left(1-m^{2}\right)\left([3]^{2}-m^{2}\right) \ldots\left([2 r-1]^{2}-m^{2}\right) x^{2 r+1}}{[2 r+1]!}
$$

## Therefore

$$
f=f_{0}+f_{1}+f_{2}+\ldots+f_{r}+\ldots \text { gives }
$$

$$
f(x)=x+\frac{\left(1-m^{2}\right) x^{3}}{[3]!}+\frac{\left(1-m^{2}\right)\left([3]^{2}-\mathrm{m}^{2}\right) x^{5}}{[5]!}+\ldots
$$

$$
+\ldots+\frac{\left(1-m^{2}\right)\left([3]^{2}-m^{2}\right) \ldots\left([2 r-1]^{2}-m^{2}\right) x^{2 r+1}}{[2 r+1]!}
$$

$$
+\ldots
$$

If we take

$$
\begin{aligned}
f_{0} & =1 \\
f_{1} & =\frac{-m^{2} x^{2}}{[2]!} \\
f_{2} & =\frac{-m^{2}\left([2]^{2}-m^{2}\right) x^{4}}{[4]!}
\end{aligned}
$$

$$
f_{r}=\frac{-m^{2}\left([\rho]^{2}-m^{2}\right) \ldots\left([2 r-2]^{2}-m^{2}\right) x^{2 r}}{[2 r]!}
$$

Therefore $f(x)=1-\frac{m^{2} x^{2}}{[2]!}-\frac{m^{2}\left([2]^{2}-m^{2}\right) x^{4}}{[4]!} \ldots$.

$$
-\frac{\mathrm{m}^{2}\left([2]^{2}-\mathrm{m}^{2}\right) \cdots\left([2 r-2]^{2}-\mathrm{m}^{2}\right) \mathrm{x}^{2 r}}{[2 r]!}
$$

## 5. GENERAL HYPERGEOMETRIC EQUATION

## Consider the equation

$$
f(\delta) \varphi=x^{h} g(\delta) \varphi
$$

Suppose

$$
f(\delta) \varphi=f([a]) x^{a}+x^{h} g(\delta) \varphi
$$

The equations in the solution by successive approximation are now

$$
\begin{aligned}
& f(\delta) \varphi_{0}=f([a]) x^{a} \\
& f(\delta) \varphi_{1}=x^{h} g(\delta) \varphi_{0} \\
& f(\delta) \varphi_{2}=x^{h} g(\delta) \varphi_{1} \\
& \therefore \ldots \ldots \ldots \ldots \ldots \ldots
\end{aligned}
$$

$$
f(\delta) \varphi_{n}=x^{h} g(\delta) \varphi_{n-1}
$$

Solving these we have

$$
\varphi_{0} \quad=\mathbf{x}^{\mathrm{a}}
$$

which gives $f(\delta) \varphi_{1}=x^{h} g(\delta) \mathrm{x}^{\mathrm{a}}$
$=x^{h} g([a]) x^{a}$ from (3.16)
$=x^{\mathrm{ath}} g([\mathrm{a}])$
Therefore $\varphi_{1}=f^{-1}(\delta) \mathrm{x}^{\mathrm{a}+\mathrm{h}} \mathrm{g}([\mathrm{a}])$
$=g([a]) f^{-1}(\delta) x^{a+h}$

$$
\varphi_{I} \quad=\frac{g\left([a] x^{a+h}\right.}{f([a+h])} \text { by (3.16) }
$$

Then

$$
\begin{aligned}
f(\delta) \varphi_{2} & =x^{h} g(\delta) \varphi_{1} \\
& =\frac{x^{h} g(\delta) x^{a+h} g([a])}{f([a+h])} \\
& =\frac{x^{a+2 h} g([a]) g([a+h])}{f([a+h])} \text { by (3.16) }
\end{aligned}
$$

Therefore $\quad \varphi_{2} \quad=\frac{x^{a+2 h} g([a]) g([a+h])}{f([a+h]) f([a+2 h])}$ by (3.16)
and so on

$$
\varphi_{n}=\frac{g([a]) g\left([a+h) \ldots g([a+(n-1) h]) x^{a+n h}\right.}{f([a+h]) f([a+2 h]) \ldots f([a+n h])}
$$

or

$$
\varphi_{n}=\prod_{r=1}^{n} \frac{g\left([a+(r-1) h] x^{a+n h}\right.}{f([a+r h])}
$$

write

$$
\begin{aligned}
s_{n}(a)= & \varphi_{0}+\varphi_{1}+\ldots+\varphi_{n} \\
= & x^{a}+\frac{g([a]) x^{a+h}}{f([a+h])}+\frac{g([a]) g([a+h]) x^{a+2 h}}{f([a+h]) f([a+2 h])} \\
& +\cdots \\
& +\ldots+\frac{g([a]) g([a+h]) \ldots g\left([a+(n-1) h] x^{a+n h}\right.}{f([a+h]) \ldots f([a+n h])}
\end{aligned}
$$

Therefore

$$
f(\delta) s_{n}(a)=f([a]) x^{a}+x^{h} g(\delta) s_{n-1}(a)
$$

Therefore

$$
\left\{f(\delta)-x^{h} g(\delta)\right\} s_{n}(a)=f([a]) x^{a}-x^{h} g(\delta) \varphi_{n}
$$

If

$$
f([a])=0
$$

Then

$$
\left\{f(\delta)-x^{h} g(\delta)\right\} s_{n}(a)
$$

$$
=\frac{-g([a]) \ldots g([a+n h]) x^{a+(n+1) h}}{f([a+h]) \ldots f([a+n h])}
$$

If

$$
\begin{array}{ll}
f([a]) & =0 \text { we get } g([a])=0 \\
\ldots & =g([a+n h])=0 \quad \text { by }(3.69)
\end{array}
$$

Then

$$
\left\{f(\delta)-x^{h} g(\delta)\right\} s_{n}(a)=0
$$

or

$$
\begin{array}{ll}
\varphi & =s_{n}(a) \text { is a solution of } \\
f(\delta) \varphi & =x^{h} g(\delta) \varphi
\end{array}
$$

If
$\mathbf{n}->\infty$, then we get

$$
\begin{equation*}
s(a) \quad=\quad x^{a}+\frac{g([a]) x^{a+h}}{f([a+h])}+\ldots \tag{3.30}
\end{equation*}
$$

or
$\varphi \quad=\quad s(a)$ is a solution.

If $f([a])=0$ has distinct roots, we may
get many solutions.

## Convergence

To find the convergence of the sequence of these solutions we should know $f(\delta)$ and $g(\delta)$.

Suppose

$$
\begin{aligned}
& f(\delta)=f_{0} \delta^{k}+f_{1} \delta^{k-1}+\ldots \\
& g(\delta)=g_{0} \delta^{j}+g_{1} \delta^{j-1}+\ldots
\end{aligned}
$$

Therefore $\quad \frac{\varphi_{n}}{\varphi_{n-1}}=\frac{g([a+(n-1) h]) x^{h}}{f([a+n h])}$
or

$$
\frac{\varphi_{n}}{\varphi_{n-1}}=\left(\frac{g_{o}}{f_{o}}\right) x^{n}[n h]^{j-k}
$$

which is convergent when

$$
\left|\frac{\varphi_{n}}{\varphi_{n-1}}\right|<1 \text { ie. if } k>j
$$

Hence

$$
\frac{\varphi_{n}}{\varphi_{n-1}} \rightarrow 0 \text { in this case }
$$

Therefore the solution (3.30) is convergent for all finite $x^{h}$.

And

$$
\frac{\varphi_{n}}{\varphi_{n-1}} \rightarrow\left(\frac{g_{0}}{f_{0}}\right) \quad x^{h} \text { if } k=j
$$

Therefore it is convergent if

$$
\left|x^{h}\right|<\left|\frac{f_{0}}{g_{0}}\right|
$$

and if $k<j$ it is divergent except at $\mathrm{x}^{\mathrm{h}}=0$

## Singularities

When $k=j$, the exceptional points are given by

$$
\left|x^{h}\right|=\left|\frac{f_{0}}{g_{0}}\right|
$$

Let

$$
h=1 \text { and } x=M x^{\prime} \text { where }
$$

$$
M=\left(\frac{f_{0}}{g_{0}}\right)^{\frac{I}{h}}
$$

If we take $f_{0}, g_{0}=I$, then $f, g$ are of the forms

$$
\begin{aligned}
& f(\delta)=\delta^{k}+f_{1} \delta^{k-1}+f_{2} \delta^{k-2}+\ldots \\
& g(\delta)=\delta^{k}+g_{1} \delta^{k-1}+\ldots \text { since } k=j
\end{aligned}
$$

The limits of convergence of the series are now $|x|=1$.

## Theorem 5

If $z$ is a solution of the basic difference equation

$$
\begin{equation*}
q^{-a}(\delta-[a]) f(\delta) z=x^{m} g(\delta) z \tag{3.31}
\end{equation*}
$$

then $\quad \varphi=\underset{s=0}{\pi-1} q \frac{-r[2 a+(r-1) m]}{2}\{\delta-[a+s m]\}$
is a solution of the basic difference equation

$$
\begin{equation*}
q^{-(a+r m)}\{\delta-[a+r m]\} f(\delta) \varphi=x^{m} \delta(\delta) \varphi \tag{3.33}
\end{equation*}
$$

Proof $q^{-(a+r m)}\{\delta-[a+r m]\} f(\delta) \varphi$

$$
\begin{aligned}
& =-(a+r m)\{\delta-[a+r m]\} f(\delta) \\
& \left.\underset{\substack{r=1}}{r-1} \frac{-r\{2 a+(r-1) m}{2}\right\}\{(\delta-[a+s m])\} z \text { by (3.32) }
\end{aligned}
$$

$$
\begin{aligned}
& =q^{-(a+r m)}-\frac{r\{2 a+(r-1) m}{2}\{\delta-[a+r m]\} \\
& \underset{s=0}{r-1}\{\delta-[a+s m]\} f(\delta) z . \\
& =\frac{-(r+1)\{2 a+r m \bar{\zeta}}{2} \underset{s=\alpha}{r}\{\delta-[a+s m]\} f(\delta) z \\
& =q^{-r\{2 a+(r+1) m} \frac{2}{q^{-a}(\delta-[a])} \underset{s=1}{\pi}\{\delta-[a+s m]\} f(\delta) z \\
& =q^{-r\{2 a+(r+1) m} \frac{\{ }{2} \underset{\substack{x=1}}{r}\{\delta-[a+s m]\} q^{-a}(\delta-[a]) f(\delta) z \\
& \left.=\frac{-r\{2 a+(r+1) m}{2}\right\} \underset{\pi}{r}\{\delta-[a+s m]\} x^{m} g(\delta) z \text { from (3.31) } \\
& \left.=x^{m} \frac{-r\{2 a+(r-1) m}{2}\right\} \underset{s=0}{r-1}\{\delta-[a+s m]\} g(\delta) z \\
& \# x^{m} g(8) \varphi \text { from (3.32) }
\end{aligned}
$$

## BASIC ADJOINT DIFFERENCE OPERATORS

Associated with the theory of basic commutative difference operators is that of basic adjoint operators which are also of importance in the theory of basic difference equations. Hence we define the basic adjoint difference operator $P_{m}^{*}$ of $P_{m}$ and establiuh some of their properties analogous to Chaundy [1]. We also define basic normal difference operators and basic self adjoint operators on the lines of Coddington [1] and construct some examples. And we derive the result that if an operator $P_{m}$ commutes with a first order operator $Q_{1}$ it is a polynomial in terms of $Q_{1}$.

1. Definitions
a) Basic adjoint difference operator

$$
\text { If } P_{m}=\sum_{k=0}^{m} a_{k}(x) \theta^{k}(\ldots) \text {, then its basic adjoint }
$$

$P_{m}$ *is defined as

$$
\begin{equation*}
P_{m}^{*}=\sum_{k=0}^{m}(-1)^{k_{\theta} k^{k}} a_{k}(x)(\ldots) \tag{4.1}
\end{equation*}
$$

## b) Basic normal operator

An operator $P_{m}$ is called basic normal if

$$
\begin{aligned}
& P_{m} P_{m}^{*}=P_{m}^{*} P_{m} \text { in the sense that } \\
& P_{m} P_{m}^{*} f=P_{m}^{*} P_{m} f
\end{aligned}
$$

c) Basic self-adjoint operator

An operator $P_{m}$ is called basic self-adjoint if $P_{m}=P_{m}{ }^{*}$.
2. BASIC NORMAL OPERATORS

## Theorem 1

In general $P_{m} P_{m}^{*} \neq P_{m}^{*} P_{m}$

Proof

$$
\begin{aligned}
P_{m} & =\sum_{k=0}^{m} a_{k}(x) \theta^{k}(\ldots) \\
P_{m}^{*} & =\sum_{k=0}^{m}(-1)^{k} \theta^{k}\left[a_{k}(x)(\ldots)\right]
\end{aligned}
$$

$$
\begin{align*}
& P_{m} P_{m}^{*} f \quad=\left[\sum_{k=0}^{m}(-1)^{k} a_{0}(x) \theta^{k} a_{k}(x)+\sum_{k=0}^{m}(-1)^{k} a_{1}(x) .\right. \\
& \left.\theta^{k+1} a_{k}(x)+\ldots+(-1)^{m} a_{m}(x) \theta^{m} a_{m}(x)\right] f \\
& +\sum_{k=1}^{m}(-1)^{k}\left(\frac{k}{k-1}\right) q^{q} q^{-(k-1)} a_{0}(x) e^{k-1} a_{k}(q x)+\ldots \\
& +\left(\begin{array}{c}
m-1
\end{array}{ }_{q^{q}} q^{-(m-1)} a_{m}(x) \theta^{m-1} a_{o}(q x)\right] \theta f \\
& +\ldots+\left[(-1)^{m} a_{0}(x) a_{m}\left(q^{m} x\right)+\ldots+(-1)^{m} a_{m}(x) .\right. \\
& \left.\theta^{m} a_{m}\left(q^{m} x\right)\right] \theta^{m} f+\ldots+(-1)^{m} a_{m}(x) a_{m}\left(q^{2 m} x\right) \theta^{2 m_{f}} \tag{4.2}
\end{align*}
$$

$$
\begin{align*}
P_{m}^{*} P_{m}^{f}= & {\left[a_{0}^{2}(x)-a_{1}(q x) \theta a_{0}(x)-\theta a_{1}(x) a_{0}(x)\right.} \\
& +a_{2}\left(q^{2} x\right) \theta^{2} a_{0}(x)+(I+q) q^{-1} \theta a_{2}(q x) \theta a_{0}(x) \\
& \left.+\ldots+(-1)^{m} \sum_{j=0}^{m}\left(\frac{m}{j}\right) q_{q} q^{j(j-m)} \theta^{j} a_{m}\left(q^{m-j} x\right) \theta^{m-j} a_{0}(x)\right] f \\
& +\ldots+(-1)^{m} a_{m}\left(q^{m} x\right) a_{m}\left(q^{m} x\right) \theta^{2 m_{f}} \tag{4.3}
\end{align*}
$$

From (4.2) and (4.3) we see that the corresponding coefficients are not the same. Hence

$$
P_{m} P_{m}^{*} \neq P_{m}^{*} P_{m}
$$

## Theorem 2

$$
\text { If the coefficients of the operator } P_{m} \text { are }
$$

constants, it is normal

Proof
Let $\quad P_{m}=\sum_{k=0}^{m} a_{k} \theta^{k}(\ldots)$

Hence $\quad P_{m}^{*}=\sum_{k=0}^{m}(-1)^{k} \theta^{k} a_{k}(\ldots)$ where $\varepsilon_{k}$ are constants

Therefore $P_{m}^{*}=\sum_{k=0}^{m}(-1)^{k} a_{k} \theta^{k}(\ldots)$
And $\quad P_{m} P_{m}^{*} f=a_{0}^{2} f+\left(2 a_{0} a_{2}-a_{1}^{2}\right) \theta^{2} f+\left(2 a_{0} a_{4}-2 a_{1} a_{3}+a_{2}^{2}\right) \theta^{4} f+\ldots$

$$
\begin{align*}
& +\left[(-1)^{m} a_{a_{m}} a_{m}+(-1)^{m-1} a_{1} a_{m-1} \ldots-a_{m-1} a_{1}+a_{m} a_{o}\right] \theta^{m} \\
& +\ldots+(-1)^{m} a_{m}^{2} \theta^{2 m_{f}} \tag{4.4}
\end{align*}
$$

$P_{m}^{*} P_{m} f=a_{o}^{2} f+\left(2 a_{o} a_{2}-a_{1}^{2}\right) \theta^{2} f+\ldots+(-1)^{m} a_{m}^{2} \theta^{2 m_{f}}$

Hence from (4.4) and (4.5)

$$
P_{m} P_{m}^{*}=P_{m}^{*} P_{m}
$$

Hence the result.

## Theorem 3

If $P_{m}$ is an operator whose coefficients are
$q$-periodic functions of $x$, then

$$
\mathrm{P}_{\mathrm{m}} \mathrm{P}_{\mathrm{m}}^{*}:=\mathrm{P}_{\mathrm{m}}^{*} \mathrm{P}_{\mathrm{m}}
$$

Proof
In this case

$$
a_{k}(x)=a_{k}(q x)=\ldots a_{k}\left(q^{m} x\right)
$$

And

$$
\theta a_{k}(x)=0 \text { for all } a_{k}(x)
$$

Hence

$$
\begin{aligned}
P_{m} P_{m}^{*} f= & P_{m}^{*} P_{m} f \\
= & a_{0}^{2}(x) f+\left[2 a_{0}(x) a_{2}(x)-a_{1}^{2}(x)\right] \theta^{2} f \\
& +\ldots+(-1)^{m} a_{m}^{2}(x) \theta^{2 m_{f}}
\end{aligned}
$$

Hence the result.

## Remark

From theorems (1), (2) and (3) we see that when the coefficients are variable functions of $x$ which are not q-periodic, only some operators commute with their basic adjoints. However, we give examples of normal operators with variable coefficients which are not q-periodic.

## 3. EXAMPLES

(i) Basic normal operators
(a) Consider

$$
\begin{align*}
P_{2}= & q x^{2} \theta^{2}+x \theta-I \\
P_{2}^{*}= & q \theta^{2} x^{2}-\theta x-I \\
P_{2} P_{2}^{*} f= & \left(q x^{2} \theta^{2}+x \theta-I\right)\left(q \theta^{2} x^{2}-\theta x-I\right) f \\
= & q^{10} x^{4} \theta^{4} f+\left\{q^{9}+2 q^{8}+3 q^{7}+2 q^{6}+q^{5}-q^{4}\right\} x^{3} \theta^{3} f \\
& +\left\{q^{7}+3 q^{6}+4 q^{5}+5 q^{4}+2 q^{3}-q^{2}-2 q\right\} x^{2} \theta^{2} f \\
& +\left(q+q^{2}-2\right) x \theta f-\left(q+q^{2}-2\right) f  \tag{4.6}\\
P_{2}^{*} P_{2} f= & \left(q \theta^{2} x^{2}-\theta x-I\right)\left(q x^{2} \theta^{2} f+x \theta f-f\right)
\end{align*}
$$

$$
\begin{align*}
= & q^{10} x^{4} \Theta^{4} f+\left(q^{9}+2 q^{8}+3 q^{7}+2 q^{6}+q^{5}-q^{4}\right) x^{3} 0^{3} f \\
& +\left(q^{7}+3 q^{6}+4 q^{5}+5 q^{4}+2 q^{3}-q^{2}-2 q\right) x^{2} \theta^{2} f \\
& +\left(q+q^{2}-2\right) x \theta f-\left(q+q^{2}-2\right) f \tag{4.7}
\end{align*}
$$

From (4.6) and (4.7) $P_{2} P_{2}^{*} f=P_{2}^{*} P_{2} f$.
Hence $P_{2}$ is basic normal.
(b) Consider

$$
\begin{aligned}
P_{I} & =x \theta+I \\
P_{I}^{*} & =-\Theta x+I \\
P_{I} P_{I}^{*} f & =(x \Theta+I)(-\Theta x f+f) \\
& =(x \Theta+I)[-q x \theta f] \\
& =-q^{2} x^{2} \Theta^{2} f-2 q x \theta f \\
P_{I}^{*} P_{I} f & =(-\Theta x+I)(x \theta f+f) \\
& =-q^{2} x^{2} \theta^{2} f-2 q x \theta f
\end{aligned}
$$

Hence

$$
P_{1} P_{1}^{*} f=P_{1}^{*} P_{1} f
$$

Hence $P_{1}$ is normal.
(ii) Basic self adjoint operators
a) Consider $\quad P_{2}=\theta^{2}-(1+q) x^{-2} I$

$$
P_{2}^{*}=\theta^{2}-(1+q) x^{-2} I
$$

Hence : $\quad P_{2}=P_{2}^{*}$
Hence $P_{2}$ is self adjoint
b) Consider

$$
\begin{aligned}
& P_{2}=(1+q) \theta^{2}+x^{2} I \\
& P_{2}^{*}=(1+q) \theta^{2}+x^{2} I
\end{aligned}
$$

4. RESULTS
(1) If $P_{m}$ is a basic difference operator, then its basic adjoint is unique.
(2) If $P_{m}^{*}$ is the adjoint of $P_{m}$ and $Q_{n}^{*}$ is the adjoint of $Q_{n}$ then, $P_{m}^{*} \pm Q_{n}^{*}$ is the adjoint of $P_{m} \pm Q_{n} ; Q_{n}^{*} P_{m}^{*}$ is the adjoint of $P_{m} Q_{n}$ and $Q_{n}^{*} P_{m}^{*}-P_{m}^{*} Q_{n}^{*}$ is the adjoint of $P_{m} Q_{n}-Q_{n} P_{m}$.
(3) $\alpha \theta^{\mathrm{n}}$ and $(-\theta)^{\mathrm{n}} \alpha$ are adjoint, $\alpha$ constant or variable.
(4) $\alpha_{0} I+\alpha_{1} \theta+\alpha_{2} \theta^{2}+\ldots+\alpha_{n} \theta^{n}$, and $\alpha_{0} I-\theta \alpha_{1}+\theta^{2} \alpha_{2}+\ldots+(-\theta)^{n_{n}}{ }_{n}$ are adjoint, $\alpha_{i}$ constants $r$ r variables.
(5) $\quad \alpha_{0} \theta \alpha_{1} 0 \alpha_{2} \ldots \theta \alpha_{n}$ and $(-1)^{n} \alpha_{n} \theta \ldots \alpha_{2} \theta \alpha_{1} \theta \alpha_{0}$ are adjoints, $\alpha_{i}$ constants or variables.
(6) $\left(\theta-\alpha_{1}\right)\left(\theta-\alpha_{2}\right) \ldots\left(\theta-\alpha_{n}\right)$ and $(-1)^{n}\left(\theta+\alpha_{n}\right) \ldots\left(\theta+\alpha_{2}\right)\left(\theta+\alpha_{1}\right)$ are adjoints, $\alpha_{i}$ constants or variables.
(7) $\alpha_{0} \theta_{1} \theta \alpha_{2}{ }^{\theta \alpha_{1}}{ }^{\theta} \alpha_{0}$ is identical with its adjoint and is therefore self-adjoint. $\alpha_{i}$ constants or variables. Proof of the above statements, being easy, are omitted.
5. THE CHARACTERISTIC IDENTITY $F\left(P_{m}{ }^{*}, Q_{n}{ }^{*}\right)=0$

## Theorem 4

If $P_{m}$ and $Q_{n}$ are commutative then $P_{m}{ }^{*}$ and $Q_{n}{ }^{*}$, their adjoints, are also commutative and $F\left(P_{m}^{*}, Q_{n}^{*}\right)=0$

Proof

$$
\begin{aligned}
& \text { If } P_{m} \text { and } Q_{n} \text { are commutative then } \\
& Q_{n} P_{m}-P_{m} Q_{n}=0 \text { and } F\left(P_{m}, Q_{n}\right)=0 \text { by }(2.36)
\end{aligned}
$$

Now by result (2)

$$
P_{m}^{*} Q_{n}^{*}-Q_{n}^{*} P_{m}^{*} \text { is adjoint to } Q_{n} P_{m}-P_{n} Q_{m}
$$

Let $Y$ be a ammon solution of

$$
\left(P_{m}-g I\right) f=0 \text { and }\left(Q_{n}-h I\right) f=0
$$

Then $Y$ is a common solution of

$$
\left(P_{m}^{*}-g I\right) f=0 \text { and }\left(Q_{n}^{*}-h I\right) f=0
$$

Operating on $Y$ with the operator $P_{m}^{*} Q_{n}^{*}-Q_{n}^{*} P_{m}{ }^{*}$ We have

$$
\begin{aligned}
\left(P_{m}^{*} Q_{n}^{*}-Q_{n}^{*} P_{m}^{*}\right) Y & =P_{m}^{*} h Y-Q_{n}^{*} g Y \\
& =\text { ghY }-h g Y \\
& =0
\end{aligned}
$$

Hence $\left(P_{m}^{*} Q_{n}^{*}-Q_{n}^{*} P_{m}^{*}\right) Y=0$ has infinitely many distinct solutions. Hence $P_{m}^{*} Q_{n}^{*}-Q_{n}{ }^{*} P_{m}^{*}=0$. Hence $P_{m}^{*}$ and $Q_{n}^{*}$ commute with each other.

So $F\left(P_{m}^{*}, Q_{n}{ }^{*}\right)=0$ by (2.36)
Hence the result.

## Example

$$
\begin{aligned}
& \text { Consider } P_{2}=\theta^{2}, Q_{3}=\theta^{3} \\
& \text { Hence } \quad \begin{aligned}
F(g, h) & =g^{3}-h^{2} \text { by }(3.10) \\
\text { Therefore } F\left(P_{2}, Q_{3}\right) & =P_{2}^{3}-Q_{3}^{2}=\left(\theta^{2}\right)^{3}-\left(\theta^{3}\right)^{2} \\
& =0 \\
& =\theta^{2} \\
P_{2}^{*} & =-\theta^{3}
\end{aligned}
\end{aligned}
$$

$F(g, h)=\left|\begin{array}{rrrrr}0 & 0 & 1 & 0 & -g \\ 0 & 1 & 0 & -g & 0 \\ 1 & 0 & -g & 0 & 0 \\ 0 & -1 & 0 & 0 & -h \\ -1 & 0 & 0 & -h & 0\end{array}\right|=g^{3}-h^{3}$
Hence

$$
\begin{aligned}
F\left(P_{2}^{*}, Q_{3}^{*}\right) & =\left(P_{3}^{*}\right)^{3}-\left(Q_{2}^{*}\right)^{2} \\
& =\left(\theta^{2}\right)^{3}-\left(-\theta^{3}\right)^{2} \\
& =0
\end{aligned}
$$

6. OPERATOR $P_{m}$ AS POLYNOMIAL IN $Q_{1}$ A FIRST ORDER BASIC DIFFERENCE OPERATOR

## Theorem 5

If a first order basic difference operator $Q_{1}$ commutes with

$$
P_{m}=\sum_{k=0}^{m} a_{k}(x) \theta^{k}(\ldots)
$$

Then

$$
P_{m}=\sum_{k=0}^{m} A_{k}(x) Q_{l}^{k}
$$

## Proof

$$
\begin{gathered}
\text { Suppose } P_{m} \text { and } Q_{I} \text { commute where } \\
\qquad Q_{I}=x \theta+I
\end{gathered}
$$

Then

$$
\begin{align*}
P_{m} Q_{1} & =Q_{1} P_{m}=a_{0}(x) I+\left[x a_{0}(x)+2 a_{1}(x)\right] \theta \\
& +\left[q x a_{1}(x)+(2+q) a_{2}(x)\right] \theta^{2}+\ldots \\
& +\ldots+\left[\left(\frac{m}{l}\right)_{q} a_{m}(x)+a_{m}(x)\right] \theta^{m} \\
& +q^{m} x a_{\text {in }}(x) \theta^{m+1} \tag{4.8}
\end{align*}
$$

Now let

$$
\begin{align*}
P_{r n}= & \sum_{k=0}^{m} A_{k}(x) Q_{1}^{k} \\
= & A_{0}(x) I+A_{1}(x)(x \theta+I) \\
& +A_{2}(x)\left[q x^{2} \theta^{2}+3 x \theta+I\right]+\ldots \\
& +\ldots+A_{m}(x)(x \theta+I)^{m} \tag{4.9}
\end{align*}
$$

Comparing coefficients of $I, \theta, \theta^{2} \ldots \theta^{m} O$ (4.8) and (4.9) we get

$$
\begin{aligned}
& A_{0}(x), A_{1}(x) \ldots A_{m}(x) \text { in terms of } a_{o}(x), a_{1}(x) \ldots \\
& a_{m}(x) .
\end{aligned}
$$

Hence the result.

## Example

$$
\begin{aligned}
\text { Let } P_{2} & =q x^{2} \theta^{2}-(1+q) x \theta+(1+q) I \\
Q_{1} & =x \theta+I .
\end{aligned}
$$

Then

$$
\begin{align*}
P_{2} Q_{1}= & Q_{1} P_{2}=q^{3} x^{3} \theta^{3}+q x^{2} \theta^{2} \\
& -(1+q) x \theta+(1+q) I . \tag{4.10}
\end{align*}
$$

Let

$$
\begin{align*}
P_{2}= & a(x) Q_{1}^{2}+b(x) Q_{I}+c(x) I \\
= & a(x) q x^{2} \theta^{2}+\{3 a(x)+b(x)\} x \theta \\
& +\{a(x)+b(x)+c(x)\} I . \tag{4.11}
\end{align*}
$$

Comparing coefficients of $I, \theta, \theta^{2}$ from (4.10) and (4.11) we get

Hence

$$
\begin{aligned}
& a(x)=1 \\
& b(x)=-(q+4) \\
& c(x)=2 q+4
\end{aligned}
$$

$$
P_{2}=Q_{1}^{2}-(q+4) Q_{1}+(2 q+4) I
$$

Therefore $P_{2}$ is a polynomial in $Q_{1}$. But this is not true for $Q_{1}^{*}$. Since

$$
\begin{aligned}
& Q_{1}^{*}=-\theta x+I \\
& P_{2} Q_{1}^{*}=Q_{1}^{*} P_{2}=q^{4} x^{3} \theta^{3} f
\end{aligned}
$$

Hence from (4.11) and (4.12) we see that $a(x), b(x)$, $c(x)$ are zeros. Therefore we cannot write $P_{2}$ as a polynomial in $Q_{1}^{*}$. Now we consider $P_{2}^{*}$ and see that $P_{2}^{*}$ cannot be written as a polynomial in $Q_{1}^{*}$.

$$
\begin{align*}
P_{2}^{*}= & q \theta^{2} x^{2}+(1+q) \theta x+(1+q) I \\
Q_{1}^{*}= & -\theta x+I \\
P_{2}^{*} Q_{1}^{*}= & Q_{1}^{*} P_{2}^{*} \\
= & -q^{8} x^{3} \theta^{3}-\left(q^{3}+2 q^{4}+2 q^{5}+2 q^{6}+q^{7}\right) x^{2} \theta^{2} \\
& -\left(4 q^{2}+3 q^{3}+2 q^{4}+q^{5}+2 q\right) x \theta . \tag{4.13}
\end{align*}
$$

If we write

$$
\begin{align*}
P_{2}^{*}= & a(x) Q_{1}^{* 2}+b(x) Q_{1}^{*}+c(x) I \\
= & q^{3} a(x) x^{2} \theta^{2}+\left\{\left(q^{2} a(x)-q b(x)\right\} x \theta\right. \\
& +c(x) I . \tag{4.14}
\end{align*}
$$

Comparing (4.13) and (4.14) we get

$$
\begin{aligned}
& c(x)=0 \\
& a(x)=-\left(1+2 q+2 q^{2}+2 q^{3}+q^{4}\right) \\
& b(x)=3 q+q^{2}-q^{4}+2-q^{5} .
\end{aligned}
$$

But from (4.14) it is clear that this is not true. Hence eventhough $P_{2}^{*} Q_{1}{ }^{*}=Q_{1}{ }^{*} P_{2}{ }^{*}, P_{2}^{*}$ is not a polynomial in $Q_{1}$, since $Q_{1}$ is not symmetric.

## 7. APPLICATION OF ADJOINT OPERATORS

## Theorem 6

If the complete solution of the basic difference equation $P_{m} \varphi=0$ is given then the adjoint equation $P_{m}^{*} \varphi=0$ can be solved. Further the solutions can be expressed explicitly in terms of those of the other.

## Proof

In results (5) and (6) of section 4 we see that $\alpha_{0} \theta \alpha_{1} \theta \alpha_{2} \ldots \theta \alpha_{n}$ and $(-1)^{n} \alpha_{n}{ }^{\theta} \ldots \alpha_{2} \theta \alpha_{1} \theta \alpha_{0}$ are adjoints and $\left(\theta-\alpha_{1}\right)\left(\theta-\alpha_{2}\right) \ldots\left(\theta-\alpha_{n}\right)$ and $(-1)^{n}\left(\theta+\alpha_{n}\right) \ldots\left(\theta+\alpha_{2}\right)$ $\left(\theta+\alpha_{1}\right)$ are adjoints.

$$
\begin{aligned}
& P_{m}^{\varphi}=0 \text { gives } \\
& \sum_{k=0}^{m} a_{k} \theta^{k} \varphi=0
\end{aligned}
$$

If $Y_{1}, Y_{2}, \ldots, Y_{m}$ are a linearly independent solutions, then

$$
\mathrm{Y}=\mathrm{c}_{1} \mathrm{Y}_{1}+\mathrm{c}_{2} \mathrm{Y}_{2}+\ldots+\mathrm{c}_{\mathrm{m}} \mathrm{Y}_{\mathrm{m}}
$$

If these $m$ functions are not linearly independent, then
constanc $c_{1}, c_{2}, \ldots, c_{m}$ may be determined so that

$$
c_{1} Y_{1}+c_{2} Y_{2}+\ldots+c_{m} Y_{m}=0 \text { identically }
$$

Difforentiating the above ation (m-1) times

$$
\begin{aligned}
& c_{1} \theta Y_{1}+o_{2} \theta Y_{2}+\ldots+c_{m} \theta Y_{m}-=0 \\
& c_{1} \theta^{2} Y_{1}+c_{2} \theta^{2} Y_{2}+\ldots+c_{m} \theta^{2} Y_{m}=0 \\
& \text { •••••••••••••••••••• } \\
& c_{1} \theta^{m-1} Y_{1}+c_{2} \theta^{m-1} Y_{2}+\ldots+c_{m} \theta^{m-I_{Y}}{ }_{m}=0
\end{aligned}
$$

Hence

$$
\Delta=\left|\begin{array}{cccc}
\mathrm{Y}_{1} & \mathrm{Y}_{2} & \cdots & \mathrm{Y}_{\mathrm{m}}  \tag{4.15}\\
\theta \mathrm{Y}_{1} & \theta \mathrm{Y}_{2} & \cdots & \theta \mathrm{Y}_{\mathrm{m}} \\
\cdot \cdots & \cdot \cdots \cdot & \cdot & \cdot \\
\cdot \cdots \cdot & \cdot & \cdot & \cdot \\
\theta^{\mathrm{m}-I_{\mathrm{Y}_{1}}} & \theta^{\mathrm{m}-I_{Y_{2}}} & \cdot & \theta^{\mathrm{m}-I_{Y_{m}}}
\end{array}\right|
$$



Then we can show that $\Delta_{1} / \Delta, \Delta_{2} / \Delta \cdots \Delta_{m} / \Delta^{\text {form a }}$ set of linearly independent solutions of the adjoint equation $P_{m}^{*} \varphi=0$.

Let

$$
\Delta_{1} / \Delta=x_{1}\left(\Delta_{2} / \Delta\right)=x_{2}, \cdots \Delta_{m} / \Delta=x_{m}
$$

Then the Wronskian of these $m$ functions is

$$
\left.\begin{array}{|cccc}
\mathrm{X}_{1} & \mathrm{X}_{2} & \cdots & \mathrm{X}_{\mathrm{m}} \\
\theta \mathrm{X}_{1} & \theta \mathrm{X}_{2} & \cdots & \theta \mathrm{X}_{\mathrm{m}} \\
\cdot & \cdot & \cdots & \cdot \\
\cdot & \cdot & \cdots & \cdot \\
\theta^{m-1} \mathrm{X}_{1} & \theta^{m-1} X_{2} & \cdots & \theta^{m-1} X_{m}
\end{array} \right\rvert\,
$$

$$
\text { nd } \quad \Delta^{-1} \neq 0 .
$$

Hence the $m$ functions $X_{1}, X_{2}, \ldots, X_{m}$ are linearly independent. Now we prove that $\mathrm{X}_{1}, \mathrm{X}_{2}, \ldots, \mathrm{X}_{\mathrm{m}}$ are the solutions of $P_{m}{ }^{*} \varphi=0$ or the solution of the equation

$$
\sum_{k=0}^{m} \quad(-1)^{k} \theta^{k} a_{k} \varphi=0 .
$$

Now the equation whose solutions are $Y_{1}, Y_{2}, \ldots, Y_{m}$ is say
$R_{I} Y=\Delta_{I}^{-1}\left|\begin{array}{cccc}\mathrm{Y} & \mathrm{Y}_{2} & \cdots & \mathrm{Y}_{\mathrm{m}} \\ \theta \mathrm{Y} & \theta \mathrm{Y}_{2} & \cdots & \theta \mathrm{Y}_{\mathrm{m}} \\ \cdot & \cdot & \cdots & \cdot \\ \cdot & \cdot & \cdots & \cdot \\ \theta^{m-I_{Y}} & \theta^{m-I_{Y_{2}}} & \cdots & \theta^{\mathrm{m}-I_{Y}}\end{array}\right|$
where $R_{l}$ is the operator with leading term $\theta^{m-l}$. We write this with the coefficient of $\theta^{m-I_{Y}}$ as unity. Then

$$
\left(\mathrm{P}_{\mathrm{m}}-\theta \mathrm{R}_{\mathrm{I}}\right) \varphi=0
$$

is also an equation of order $m$-l whose roots are $Y_{2} \ldots Y_{m}$.

Hence

$$
P_{m}-\theta R_{l}=\alpha R_{l} \text { for some } \alpha
$$

Therefore

$$
P_{m} \quad=(\theta+\alpha I) R_{I}
$$

Hence

$$
(\theta+\alpha I) R_{1} Y_{1}=P_{m} Y_{1}=0
$$

Now $R_{I} Y_{I}=\Delta_{1}^{-1}\left|\begin{array}{cccc}Y_{1} & Y_{2} & \ldots & Y_{m} \\ \theta Y_{1} & \theta Y_{2} & \ldots & \theta Y_{m} \\ \cdot & \cdot \cdot & \ldots & \cdot \\ \theta^{m-I_{Y_{1}}} & \theta^{m-I_{Y_{2}}} & \ldots & \theta^{m-I_{Y_{m}}}\end{array}\right|=\Delta \Delta \Delta_{1}$.

Thus $(\theta+\alpha I)\left(\Lambda / \Lambda_{1}\right)=0$.

Therefore

$$
\begin{equation*}
(\theta-\alpha I)\left(\Delta_{1} / \Delta\right)=0 \tag{4.16}
\end{equation*}
$$

But

$$
\begin{aligned}
\mathbf{P}_{m}^{*} & =-\theta R_{1}(\theta-\alpha I) \\
& =-\Theta R_{1}(\theta-\alpha I)
\end{aligned}
$$

## - G3498-

Hence

$$
P_{m}^{*}\left(\Delta_{1} / \Delta\right)=0 .
$$

Therefore in a similar manner

$$
P_{m}^{*}\left(\Delta_{r} / \Delta\right)=0 \text { for every } r
$$

Hence the result .

## Generalisation of theorem 6

$$
\text { If } P_{m} \text { and } Q_{n} \text { are commutative and have }
$$

leading terms $\theta^{m}, \theta^{n}$ respectively and if $y_{r}$ is the solution of

$$
\left(P_{m}-g I\right) \varphi=0, \quad\left(Q_{n}-h_{r} I\right) \varphi=0(r=1, \ldots, m)
$$

then $\triangle_{r} / \triangle$ is a solution common to the adjoint equations

$$
\begin{array}{r}
\left(P_{m}^{*}-g I\right) \varphi=0,\left(Q_{n}^{*}-h_{r} I\right) \varphi=0 \\
r=1, \ldots, m
\end{array}
$$

Proof
We have seen that

$$
(\theta-\alpha I)\left(\Delta_{1} / \Delta\right)=0 \text { from }(4.16)
$$

Now

$$
R_{1} Q_{n} Y_{r}=R_{1} h_{r} Y_{r}=0(r=2, \ldots, m)
$$

Hence $R_{1} Q_{n}=Q_{1} R_{I}$, where $Q_{I}$ is some operator.
Hence $\quad(\theta+\alpha I) Q_{I} R_{I}=(\theta+\alpha I) R_{I} Q_{n}=\left(P_{m}-g I\right) Q_{n}$

$$
\begin{align*}
& =Q_{n}\left(P_{m}-g I\right) \\
& =Q_{n}(\theta+\alpha I) R_{I} . \tag{4.17}
\end{align*}
$$

Hence

$$
(\theta+\alpha I) Q_{I}=Q_{n}(\theta+\alpha I)
$$

But

$$
\left(Q_{1}-h_{1} I\right) R_{1} Y_{1}=R_{1}\left(Q_{n}-h_{I} I\right) Y_{1}=0 .
$$

Therefore $\left(Q_{1}-h_{1} I\right)\left(\Delta / \Delta_{1}\right)=0$.

Hence for some operator $s_{1}$

$$
Q_{1}-h_{1} I=s_{1}(\theta+\alpha I)
$$

From (4.17)

$$
\begin{aligned}
\quad\left(Q_{n}-h_{1} I\right)(\theta+\alpha I) & =(\theta+\alpha I)\left(Q_{1}-h_{1} I\right) \\
& =(\theta+\alpha I) s_{1}(\theta+\alpha I) . \\
\text { And so } Q_{n}-h_{1} I & =(\theta+\alpha I) s_{i} .
\end{aligned}
$$

By taking adjoint we have

$$
Q_{n}^{*}-h_{1} I=-\theta s_{1}(\theta-\alpha I)
$$

Therefore

$$
\left(Q_{n}^{*}-h_{1} I\right)\left(\Delta_{I} / \Delta\right)=0 .
$$

Hence the result.

## CHAPTER V

BIBASIC COMMUTATIVE DIFFERENCE OPERATORS

We can extend the theory of basic commutative difference operators to bibasic commutative difference operators. If $f(x, y)$ is a function of two variables in $R^{2}$ and if $D_{p x}$ and $D_{q y}$ denote the difference operators we see that these difference operators are commutative. But all bibasic polynomial difference operators are not commutative. Hence in this chapter an attempt is made to study the conditions under which the bibasic difference operators are commutative. Also we define some special bibasic commutative difference operators and study their properties. Using these operators we solve some bibasicdifference equations.

1. BIBASIC DIFFERENCE OPERATORS AND THEIR PROPERTIES

$$
\text { Let } x=p^{m} x_{0}, y=q^{n} y_{0}, p \neq q \text { and } p, q \neq 1
$$ are fixed; where $m \varepsilon Z, n \varepsilon Z ; X_{0}>0, y_{0}>0$ fixed.

$$
\text { Let } f(x, y)=\sum_{j, k=0}^{m} \alpha_{j, k} x^{k} y^{j}, k+j \leqslant m \text {, where }
$$

$|x|<x_{0},|y|<y_{0}$.

We define the bibasic difference operators as:

$$
\begin{align*}
& D_{p x} f(x, y)=\frac{f(x, y)-f(p x, y)}{(1-p) x}  \tag{5.1}\\
& D_{q y} f(x, y)=\frac{f(x, y)-f(x, q y)}{(1-q) y} . \tag{5.2}
\end{align*}
$$

We see that $D_{p x}$ and $D_{q y}$ are commutative. Consider the bibasic polynomial difference operators

$$
\begin{aligned}
& P_{m}=\sum_{k, j=0}^{m} a_{k, j} D_{p x}^{k} D_{q y}^{j}, k+j \leqslant m \\
& Q_{n}=\sum_{k, j=0}^{n} b_{k, j} D_{p x}^{k} D_{q y}^{j}, k+j \leqslant n .
\end{aligned}
$$

Convergence of

$$
\begin{equation*}
\sum_{k, j=0}^{m} a_{k, j} D_{p x}^{k} D_{q y}^{j} f(x, y) \text { as } m \rightarrow \infty \tag{5.3}
\end{equation*}
$$

depends on the nature of $f(x, y)$. We cannot therefore discuss the convergence of the operator by itself apart from knowledge of the operand. We can see that (5.3) converges if $f(x, y)$ converges. Hence we can consider bibasic difference operators of finite or infinite order.

If the operand is a polynomial of $n^{\text {th }}$ degree in $x$ and $y$ these infinite operators terminate at $n$. In other cases we treat infinite operators as purely symbolic.

Now if we consider three bibasic polynomial difference operators $P, Q, R$ we see that

$$
\begin{array}{ll}
P+Q & =Q+P \\
P+(Q+R) & =(P+Q)+R \\
P(Q R) & =(P Q) R \\
P(Q+R) & =P Q+P R .
\end{array}
$$

Hence these operators obey the fundamental laws of arithmetic combination except the commutative law. In general $P Q \neq Q P$. For example, consider

$$
\begin{aligned}
& P=a_{0}(x, y) I+a_{1}(x, y) D_{p x}+a_{2}(x, y) D_{q y} \\
& Q=b_{0}(x, y) I+b_{1}(x, y) D_{p x}+b_{2}(x, y) D_{q y} .
\end{aligned}
$$

Hence $P Q=\left[a_{0}(x, y) b_{0}(x, y)+a_{1}(x, y) D_{p x} b_{0}(x, y)\right.$

$$
\begin{aligned}
& \left.+a_{2}(x, y) D_{q y} b_{0}(x, y)\right] I \\
+ & {\left[\cdot_{0}(x, y) b_{1}(x, y)+a_{1}(x, y) b_{0}(p x, y)\right.} \\
+ & \left.i_{1}(x, y) D_{p x} b_{1}(x, y)+a_{2}(x, y) D_{q y} b_{1}(x, y)\right] D_{p x}
\end{aligned}
$$

$$
\begin{align*}
+ & {\left[a_{1}(x, y) b_{1}(p x, y)\right] D_{p x}^{2}+a_{2}(x, y) b_{2}(x, q y) D_{q y}^{2} } \\
+ & {\left[a_{1}(x, y) b_{2}(p x, y)+a_{2}(x, y) b_{1}(x, q y)\right] D_{p x} D_{q y} } \\
+ & {\left[a_{0}(x, y) b_{2}(x, y)+a_{1}(x, y) D_{p x} b_{2}(x, y)\right.} \\
Q P= & \left.+a_{2}(x, y) b_{0}(x, q y)+a_{2}(x, y) D_{q y} b_{2}(x, y)\right] D_{q y}  \tag{5.4}\\
& \quad\left[b_{0}(x, y) a_{0}(x, y)+b_{1}(x, y) D_{p x} a_{0}(x, y)+\right. \\
& \left.+b_{2}(x, y) D_{q y} a_{0}(x, y)\right] I \\
+ & {\left[b_{0}(x, y) a_{1}(x, y)+b_{1}(x, y) a_{0}(p x, y)\right.} \\
& \left.+b_{1}(x, y) D_{p x} a_{1}(x, y)+b_{2}(x, y) D_{q y} a_{1}(x, y)\right] D_{p x} \\
+ & {\left[b_{0}(x, y) a_{2}(x, y)+b_{1}(x, y) D_{p x} a_{2}(x, y)\right.} \\
+ & \left.+b_{1}(x, y) a_{0}(x, q y)+b_{2}(x, y) D_{q y} a_{2}(x, y)\right] D_{q y} \\
+ &
\end{align*}
$$

From (5.4) and (5.5) we see that

$$
\mathrm{PQ}_{\mathrm{Q}} \neq \mathrm{QP}
$$

2. BIBASIC COMMUTATIVE DIFFERENCE OPERATORS
a) Operators $P_{m}$ and $Q_{n}$ are commutative if their coefficients are constants

$$
\left(P_{m} Q_{n}\right) f=\left(\sum_{k, j=0}^{m} a_{k, j} D_{p x}^{k} D_{q y}^{j}\right)\left(\sum_{k, j=0}^{n} b_{k, j} D_{p x}^{k} D_{q y}^{j}\right) f
$$

where $a_{k, j}$ and $b_{k, j}$ are constants,

$$
\begin{aligned}
& =\left[a_{00} b_{00} I+\left(a_{00} b_{10}+a_{10} b_{00}\right) D_{p x}\right. \\
& +\left(a_{00} b_{01}+a_{o l} b_{00}\right) D_{q y} \\
& +\left(a_{00} b_{11}+a_{10} b_{01}+a_{01} b_{10}+a_{11} b_{00}\right) D_{p x} D_{q y} \\
& \left.+\ldots+a_{m, o} b_{n, o} D_{p x}^{m+n}+a_{o, m} b_{o, n} D_{q y}^{m+n}\right]_{f} \\
& =\left(Q_{n} P_{m}\right) f .
\end{aligned}
$$

Hence the result.
b) Operators $P_{m}$ and $Q_{n}$ are commutative if their coefficients are bi-periodic functions, ie. $p$-periodic in $x$ and $q$-periodic in $y$.

In this case $a_{0 O}(p x, y)=a_{0 O}(x, y)$

$$
a_{o O}(x, q y)=a_{o o}(x, y)
$$

and so on.
Also $D_{p x}{ }^{a_{00}}(x, y)=0=D_{q y}{ }^{a}{ }_{00}(x, y)$ and so on.

Therefore these coefficients act as constants.
Hence we get the same result as (5.6).
c) Operators $P_{m}$ and $Q_{n}$ with variable coefficients are commutative if they satisfy $\frac{(m+1)(m+2)}{2}+\frac{(n+1)(n+2)}{2}+1$ bibasic difference equations. That is if the coefficients of the two operators are related,

$$
\left(P_{m} Q_{n}\right) f=\left(\sum_{k, j=0}^{m} a_{k, j}(x, y) D_{p x}^{k} D_{q y}^{j}\right)\left(\sum_{k, j=0}^{n} b_{k, j}(x, y) D_{p x}^{k} D_{q y}^{j} f\right)
$$

and

$$
\left(Q_{n} P_{m}\right) f=\left(\sum_{k, j=0}^{n} b_{k, j}(x, y) D_{p x}^{k} D_{q y}^{j}\right)\left(\sum_{k, j=0}^{m} a_{k, j}(x, y) D_{p x}^{k} D_{q y}^{j} f\right)
$$

Hence

$$
\begin{aligned}
\left(P_{m} Q_{n}-Q_{n} P_{m}\right) f= & {\left[\sum_{k=0}^{m} a_{k, o}(x, y) D_{p x}^{k} b_{o o}(x, y)\right.} \\
& \left.-\sum_{k=0}^{n} b_{k, o}(x, y) D_{p x}^{k} a_{o o}(x, y)\right] f \\
& +\ldots+\left[a_{m, o}(x, y) b_{n, o}\left(p^{m} x, y\right)\right. \\
& \left.-b_{n, o}(x, y) a_{m, o}\left(p^{m} x, y\right)\right] D_{p x}^{m+n_{f}} \\
& +\left[a_{o, m}(x, y) b_{o, n}\left(x, q^{m} y\right)-\right. \\
& \left.-b_{o, n}(x, y) a_{o, m}\left(x, q^{n} y\right)\right] D_{q y}^{m+n} n_{f}
\end{aligned}
$$

These operators are commatative if and only if

$$
\left(P_{m} Q_{n}-Q_{n} P_{m}\right) f=0
$$

ie. we get $\quad \frac{(m+1)(m+2)}{2}+\frac{(n+1)(n+2)}{2}+1$
bibasic difference equations to be satisfied, which are

$$
\sum_{k=0}^{m} a_{k, 0}(x, y) D_{p x}^{k} b_{o O}(x, y)-\sum_{k=0}^{n} b_{k, o}(x, y) D_{p x}^{k} a_{o \circ}(x, y)=0
$$

$a_{m, 0}(x, y) b_{n, 0}\left(p^{m} x, y\right)-b_{n, o}(x, y) a_{m, o}\left(p^{n} x, y\right)=0$
$a_{0, m}(x, y) b_{o, n}\left(x, q^{m} y\right)-b_{o, n}(x, y) a_{o, m}\left(x, q^{n} y\right)=0$
Hence the result.
3. AITERNANTS OF BIBASIC DIFFERENCE LINEAR OPERATORS

If two bibasic difference operators $P$ and $Q$ are non-commutative, then $P Q-Q P$ is called their alternant.

Result 1
The alternant of two linear bibasic difference operators is also a linear bibasic difference operator.

Proof
Consider

$$
\begin{aligned}
& P=\alpha_{1}(x, y) D_{p x}+\alpha_{2}(x, y) D_{q y} \\
& Q=\beta_{1}(x, y) D_{p x}+\beta_{2}(x, y) D_{q y} .
\end{aligned}
$$

$$
\begin{aligned}
\text { Then } \mathrm{PQ}-\mathrm{QP}= & {\left[\alpha_{1}(x, y) D_{p x} \beta_{1}(x, y)+\alpha_{2}(x, y) D_{q y} \beta_{1}(x, y)\right.} \\
& \left.-\beta_{1}(x, y) D_{p x} \alpha_{1}(x, y)-\beta_{2}(x, y) D_{q y} \alpha_{1}(x, y)\right] D_{p x} \\
& +\left[\alpha_{1}(x, y) D_{p x} \beta_{2}(x, y)+\alpha_{2}(x, y) D_{q y} \beta_{2}(x, y)\right. \\
& \left.-\beta_{1}(x, y) D_{p x} \alpha_{2}(x, y)-\beta_{2}(x, y) D_{q y} \alpha_{2}(x, y)\right] D_{q y} \\
& +\left[\alpha_{1}(x, y) \beta_{1}(p x, y)-\beta_{1}(x, y) \alpha_{1}(p x, y)\right] D_{p x}^{2} \\
& +\left[\alpha_{1}(x, y) \beta_{2}(p x, y)+\alpha_{2}(x, y) \beta_{1}(x, q y)-\beta_{1}(x, y) \alpha_{2}(p x, y)\right. \\
& \left.-\beta_{2}(x, y) \alpha_{1}(x, q y)\right] D_{q y} D_{p x} \\
& +\left[\alpha_{2}(x, y) \beta_{2}(x, q y)-\beta_{2}(x, y) \alpha_{2}(x, q y)\right] D_{q y}^{2} .
\end{aligned}
$$

This is also a linear operator. Hence the result. We denote the alternant $P Q-Q P$ by ( $P, Q$ ).

Note Since ( $P, Q$ ) is linear, we can form its alternant with $P$ and with $Q$ respectively. Hence we get $\{P,(P, Q)\}$ and $\{Q,(P, Q)\}$ etc. These are again linear. Hence we get a succession of alternants in this way.

## Result 2

$$
\text { If } P, Q, R \text { are three linear bibasic operators, }
$$

then

$$
\{P,(Q, R)\}+\{Q,(R, P)\}+\{R,(P, Q)\}=0
$$

Proof being easy, is not given.

## Result 3

$$
\begin{aligned}
& \text { If } P \text { and } Q \text { are commutative, then } \\
& \{P,(Q, R)\}=\{Q,(P, R)\} .
\end{aligned}
$$

Proof

$$
\begin{align*}
\{P,(Q, R)\} & =P(Q R-R Q)-(Q R-R Q) P  \tag{5.7}\\
\{Q,(P, R)\} & =Q P R-Q R P-P R Q+R P Q \\
& =(P Q R-P R Q)-(Q R P-R Q P) \\
& =P(Q R-R Q)-(Q R-R Q) P \\
& =\{P,(Q, R)\} \tag{5.8}
\end{align*}
$$

From (5.7) and (5.8) we get the result.

## Result 4

The sequence of repeated alternants that can be constructed from a given pair of linear bibasic difference operators in general does not terminate.

## Proof

Consider two linear bibasic difference
operators

$$
\begin{aligned}
\mathrm{P} & =\mathrm{D}_{\mathrm{px}}+\mathrm{D}_{\mathrm{qy}} \\
\mathrm{Q} & =\quad x D_{p x}+y D_{q y}
\end{aligned}
$$

Then $P Q \quad \neq \quad Q P$.

Hence $\quad(Q, P)=(1-p) x D_{p x}{ }^{2}-D_{p x}-D_{q y}+(1-q) y D_{q y}{ }^{2}$.

This is a linear operator.
Hence $\{(Q, P), P\}=(1-p)^{2} x D_{p x}{ }^{3}-(1-p) D_{p x}{ }^{2}$

$$
-(1-q) D_{q y}^{2}+(1-q)^{2} y D_{q y}^{3}
$$

This is again linear and so on. We get a succession of linear operators of the form

$$
\begin{align*}
& (1-p)^{n}{ }_{x} D_{p x}^{n+1}-(1-p)^{n-1} D_{p x}^{n} \\
- & (1-q)^{n-1} D_{q y}^{n}+(1-q)^{n} y D_{q y}^{n+1} . \tag{5.9}
\end{align*}
$$

Hence the result, since (5.9) does not terminate unless $\mathrm{p}<1, \mathrm{q}<1$.

## Result 5

If $Y$ is a solution of $P f=0, Q f=0$, where $P$ and $Q$ are two bibasic linear operators, then $Y$ is a constant or is bi-periodic.

## Proof

Since $Y$ is a solution of $P f=0$ and $Q f=0$, we get $P Y=0, Q Y=0$ and hence $(Q, P) Y=0$. Hence $Y$ is a solution of $(Q, P) f=0$. Hence by results (3) and (4), Y is a solution of all repeated alternants. But if $Y$ is a solution of $n$ linearly independent bibasic linear operators in a field of $n$ variables, we get $n$ independent equations of the form

$$
\begin{aligned}
& \alpha_{11} P_{1} Y+\alpha_{12} P_{2} Y+\ldots+\alpha_{1 n} P_{n} Y=0 \\
& \cdots \cdot \ldots \cdot+\cdots \cdot \alpha_{n n} P_{n} Y=0 .
\end{aligned}
$$

This is possible only if $P_{1} Y=0, P_{2} Y=0 \ldots P_{n} Y=0$ which gives $Y=a$ constant or $Y$ is bi-periodic. Hence the result.
4. SPECIAL BIBASIC COMMUTATIVE DIFFERENCE OPERATORS

Let $\quad \begin{array}{ll}\delta_{p x} & =\mathrm{xD}_{\mathrm{px}} \\ \delta_{q y} & =\mathrm{y} D_{q y} .\end{array}$

Then we see that

$$
\delta_{p x} \delta_{q y}=\delta_{q y} \delta_{p x}
$$

Hence these operators are commutative. Now we consider the operators

$$
\begin{aligned}
& D_{p x}^{m}=p^{\frac{-m(m-1)}{2}} x^{-m}{\underset{k=0}{m-1}\left[\delta_{p x}-[k] p^{I}\right]}_{D_{q y}^{n}=q^{-\frac{n(n-1)}{2}} y^{-n}{\underset{k}{n=0}}_{n-1}^{n}\left[\delta_{q y}-[k] q^{I}\right]}
\end{aligned}
$$

Then by the same argument as in (3.3) we see that

$$
D_{p x}^{m} D_{q y}^{n}=D_{q y}^{n} D_{p x}^{m}
$$

But here there are no common factors as in (3.1) and (3.2) and hence derivation of new operators by transference of common factors is not possible in this case.

$$
\begin{aligned}
\delta_{p x}^{-1} & =D_{p x}^{-1} c x^{-1} \\
\delta_{q J}^{-1} & =D_{q y}^{-1} y^{-1}
\end{aligned}
$$

Hence if $f(\delta)_{q}=a \delta_{p x}+b \delta_{q y}+c I$.

Then

$$
\text { Then } \begin{aligned}
& f\left(\delta_{p q}\right)(x y)^{m}=\left(a x D_{p x}+b y D_{q y}+c I\right)(x y)^{m} \\
&=\left(a[m]_{p}+b[m]_{q}+c\right)(x y)^{m} \\
&=f([m])(x y)^{m} \\
& \text { If } \quad \begin{aligned}
& f\left(\delta_{p q}^{-1}\right) \\
& \text { Then } \quad f\left(\delta_{p q}^{-1}\right)(x y)^{\text {in }} \\
&=\left(a \delta_{p x}^{-1}+b \delta_{q y}^{-1}+c I\right) \\
&\left.=a \delta_{p x}^{-1}+b \delta_{q y}^{-1}+c I\right)(x y)^{m} \\
&\left.=\left[a \frac{1}{m}\right]_{p}+b \frac{1}{m}\right]_{q}^{m}+b D_{q y}^{-1} y^{-1}(x y)^{m}+c(x y)^{m}(x y)^{m}
\end{aligned}
\end{aligned}
$$

The arguments being same as (3.16) and (3.19) we leave the detailed proof.
5. SOLUTION OF BIBASIC DIFFERENCE EQUATIONS

## Theorem

Any linear combination of two solutions of a linear homogeneous bibasic difference equation if they exist is again a solution.

## Proof

We prove the theorem for the general equation of the second order. Consider the bjbasic difference equation

$$
\left[D_{p x}^{2}+C_{4} D_{q y}^{2}+C_{3} D_{p x} D_{q y}+C_{2} D_{p x}+C_{1} D_{q y}+C_{0} I\right]_{f}(x, y)=0
$$

where $c_{i}, i=0, \ldots, 4$ are constants.

If possible let

$$
\begin{align*}
{\left[D_{p x}^{2}\right.} & \left.+C_{4} D_{q y}^{2}+C_{3} D_{p x} D_{q y}+C_{2} D_{p x}+C_{1} D_{q y}+C_{o} I\right]_{f} \\
& =\left(D_{p x}+K_{1} D_{q y}+K_{2} I\right)\left(D_{p x}+K_{1} D_{q y}+K_{2}^{\prime} I\right) f \tag{5.10}
\end{align*}
$$

Hence

$$
\left(D_{p x}+K_{1} D_{q y}+K_{2} I\right) f=0
$$

and

$$
\left(D_{p x}+K_{i} D_{q y}+K_{2}^{\prime I}\right) f=0
$$

Then

$$
\left(K_{1}-K_{1}^{\prime}\right) D_{q y} f+\left(K_{2}-K_{2}^{\prime}\right) f=0
$$

ie $\quad D_{q y}{ }^{f}=\left\{\frac{K_{2}^{1}-K_{2}}{K_{1}-K_{i}^{\prime}}\right\} f$
ie $\frac{f(x, y)-f(x, q y)}{(l-q) y}=\left\{\frac{K_{2}^{1}-K_{2}}{K_{1}-K_{1}^{1}}\right\} f(x, y)$
ie $\left[1-\left\{\frac{K_{2}^{\prime}-K_{2}}{K_{1}-K_{1}}\right\}(1-q) y\right] f(x, y)=f(x, q y)$

Hence $f(x, y)=\prod_{n=0}^{\infty} \frac{f\left(x, q^{n} y\right)}{\left[i-\left\{\frac{K_{2}^{\prime}-K_{2}}{K_{1}-K_{1}^{\prime}}\right\}(1-q) q^{n} y\right]}$
exists when $q<1$.

Substituting for $D_{q y}{ }^{f}$ in the equation (5.10) we have

$$
D_{p x} f=\left\{\frac{-K_{1} K_{2}^{\prime}+K_{2} K_{i}^{\prime}}{K_{1}-K_{i}^{\prime}}\right\} f(x, y)
$$

Hence $\frac{f(x, y)-f(p x, y)}{(1-p) x}=\left\{\frac{-K_{1} K_{2}^{1}+K_{2} K_{1}^{\prime}}{K_{1}-K_{i}^{\prime}}\right\} f(x, y)$

exists when $p<1$. Let these be denoted by $f_{1}(x, y)$ and $f_{2}(x, y)$. Comparing coefficients of (5.10) we have

$$
\begin{aligned}
& \mathrm{K}_{1} \mathrm{~K}_{1}^{\prime}=\mathrm{c}_{4} \Longrightarrow \mathrm{~K}_{1}=\mathrm{c}_{4} / \mathrm{K}_{1} \\
& \mathrm{~K}_{1}+\mathrm{K}_{1}^{\prime}=\mathrm{c}_{3}=\mathrm{K}_{1}^{2}-c_{3} \mathrm{~K}_{1}+c_{4}=0
\end{aligned}
$$

1e. $\quad K_{1}=\frac{c_{3} \pm \sqrt{c_{3}^{2}-4 c_{4}}}{2}$
exists when $c_{3}{ }^{2}-4 c_{4}$ \& 0

Similarly

$$
K_{2} K_{2}^{\prime}=o_{0} \Rightarrow K_{2}=c_{0} / K_{2}^{\prime}
$$

$$
K_{2}+K_{2}^{\prime}=c_{2} \Rightarrow K_{2}^{\prime 2}-c_{2} K_{2}^{\prime}+c_{0}=0
$$

ie.
$K_{2}^{\prime}=\frac{c_{2} \pm c_{2}^{2}-4 c_{0}}{2}$
exists when $c_{2}{ }^{2}-4 i_{0} \& 0$

Then

$$
\begin{aligned}
& K_{1}=\frac{2 c_{4}}{c_{3} \pm \sqrt{c_{3}^{2}-4 c_{4}}} \text { and } \\
& K_{2}=\frac{2 c_{0}}{c_{2} \pm \sqrt{c_{2}^{2}-4 c_{o}}} \\
& K_{1} K_{2}^{\prime}+K_{2} K_{1}^{\prime}=c_{1}
\end{aligned}
$$

Then

$$
\begin{align*}
D_{p x}{ }^{2} f_{1} & +c_{4} D_{q J}{ }^{2} f_{1}+c_{3} D_{p x} D_{q y} f_{1} \\
& +c_{2} D_{p x} f_{1}+c_{1} D_{q y} f_{1}+c_{0} f_{1}=0 \tag{5.11}
\end{align*}
$$

and

$$
\begin{align*}
& D_{p x}{ }^{2} f_{2}+c_{4} D_{q y}{ }^{2} f_{2}+c_{3} D_{p x} D_{q y} f_{2} \\
& \quad+c_{2} D_{p x} f_{2}+c_{1} D_{q y} f_{2}+c_{0} f_{2}=0 \tag{5.12}
\end{align*}
$$

Multiplying (5.11) by $A_{1}$ and (5.12) by $A_{2}$ and adding we have

$$
\begin{aligned}
& D_{p x}{ }^{2}\left(A_{1} f_{1}+A_{2} f_{2}\right)+c_{4} D_{q y}{ }^{2}\left(A_{1} f_{1}+A_{2} f_{2}\right) \\
& \quad+c_{3} D_{p x} D_{q y}\left(A_{1} f_{1}+A_{2} f_{2}\right)+c_{2} D_{p x}\left(A_{1} f_{1}+A_{2} f_{2}\right) \\
& \quad+c_{1} D_{q y}\left(A_{1} f_{1}+A_{2} f_{2}\right)+c_{0}\left(A_{1} f_{1}+A_{2} f_{2}\right)=0
\end{aligned}
$$

Hence $A_{1} f_{1}+A_{2} f_{2}$ is a solution of (5.46)

Consider the bibasic difference equation

$$
\begin{aligned}
& {\left[p q \delta_{p x}^{2} \delta_{q y}^{2}+p \delta_{p x}^{2} \delta_{q y}-p \delta_{p x}^{2}\right.} \\
& +q \delta_{p x} \delta_{q y}^{2}+\delta_{p x} \delta_{q y}-\delta_{p x}-q \delta_{q y}^{2} \\
& \left.-\delta_{q y}+I\right] f(x, y)=(x y)^{3}
\end{aligned}
$$

ie. $\quad\left(\mathrm{p} \delta_{p x}{ }^{2}+\delta_{p x}-\mathrm{I}\right)\left(q \delta_{q y}{ }^{2}+\delta_{q y}-I\right) f(x, y)=(x y)^{3}$.
ie. $\left(\delta_{\mathrm{px}}{ }^{2}-I\right)\left(\delta_{\mathrm{qJ}}{ }^{2}-I\right) f(\mathrm{x}, \mathrm{y}) \quad=(\mathrm{xy})^{3}$
Hence $f(x, y)=\left(\delta_{p x}{ }^{2}-I\right)^{-1}\left(\delta_{q y}{ }^{2}-I\right)^{-1}(x y)^{3}$.

$$
=\frac{(x y)^{3}}{\left([3]_{p}^{2}-1\right)\left([3]_{q}^{2}-1\right)} \quad \text { by (5.45) }
$$

## CHATTER VI

## BIBASIC PSEUDOANALYTIC FUNCTIONS

## Bibasic pseudoanalytic functions

Discrete analytic function theory is concerned with complex valued functions defined at certain lattice points in the complex plane. Harman [l] used the lattice $\left\{\left( \pm q^{m} x_{0}, \pm q^{n} y_{0}\right)\right\}$ suitable for $q$-function theory and developed the concept of q-analytic functions. Using Harman's lattice, Mercy Jacob [l] introduced discrete pseudoanalytic functions. Kharı [․] extended Harman's q-analytic functions to bibasic analytic functions using the lattice $\left\{\left( \pm p^{m} x_{0}, \pm q^{n} y_{0}\right)\right\}$ wh.re $p$ and $q$ are not related. Here an attempt is made to establish bibasic pseucioanalytic functions using the bibasic lattice of Khan.

## 1. THE LATTICE

For convenience we consider only the first quadrant of the complex plane. We define the discrete plane $B^{\prime}$ with respect to some fixed point $z_{0}=\left(x_{0}, y_{0}\right)$, as the set of lattice points

$$
\begin{align*}
B^{\prime}=\{ & \left.\left\{p^{m} x_{o}, q^{n} y_{o}\right), m, n \in z\right\} \\
& x_{0}>0, y_{0}>0, p \neq q \text { and } \\
& p, q \neq 1 \text { fixed } \tag{6.1}
\end{align*}
$$

$z_{0}$ will be called the origin of $B^{\prime}$.

Two lattice points $z_{i}, z_{i+1} \varepsilon B^{\prime}$ are said to be " adjacent" if $z_{i+1}$ is one of $\left(p x_{i}, y_{i}\right),\left(p^{-1} x_{i}, y_{i}\right)$, $\left(x_{i}, q y_{i}\right)$ or $\left(x_{i}, q^{-1} y_{i}\right)$ where $z_{i}=\left(x_{i}, y_{i}\right)$


Let

$$
\begin{equation*}
A(z)=\left\{(p x, y),(x, q y),\left(p^{-1} x, y\right),\left(x, q^{-1} y\right)\right\} \tag{6.2}
\end{equation*}
$$

A 'discrete curve C' in $B$ ' joining $z_{o}$ and $z_{n}$ is denoted by the sequence

$$
\begin{equation*}
c=\left\langle z_{0}, z_{1}, \ldots, z_{n}\right\rangle \tag{6.3}
\end{equation*}
$$

where $z_{i}, z_{i+1}, i=0,1, \ldots, n-1$ are adjacent points of $\mathrm{B}^{\prime}$.

If points are distinct $\left(z_{i} \neq z_{j}\right.$, if $\left.i \neq j\right)$, then the discrete curve $C$ is said to be simple.
'A discrete closed curve C' in $B^{\prime}$ is a discrete curve $\left\langle z_{0}, z_{1}, \ldots, z_{n}\right\rangle$ where $\left\langle z_{0}, z_{1}, \ldots, z_{11-1}\right\rangle$ is simple and $z_{0}=z_{n}$.

$$
\begin{equation*}
T(z)=\{(x, y),(p x, y),(x, q y)\} \text { is called the } \tag{6.4}
\end{equation*}
$$

triad of $z$.

$$
\begin{equation*}
S(z)=\{(x, y),(p x, y),(p x, q y),(x, q y)\} \tag{6.5}
\end{equation*}
$$

is called the " bibasic set" with respect to $z \varepsilon B^{\prime}$.
The discrete closed curve around $S(z)$ is $<(x, y),(p x, y)$, ( $p x, q y$ ), ( $x, q y$ ), ( $x, y$ ) $>$ and this order of points is taken as the positive direction. A discrete domain D is composed of a union of bibasic sets.

Therefore

$$
\begin{equation*}
D=\prod_{i=1}^{n} S\left(z_{i}\right) \tag{6.6}
\end{equation*}
$$

If $\overline{\mathrm{C}}$ is the closed curve formed by joining adjacent points of the discrete closed curve $C$, then $\overline{\mathrm{C}}$ encloses certain points of $\mathrm{B}^{\prime}$, denoted by $\operatorname{Int}(\mathrm{C})$.

A "finite discrete domain" D is defined as

$$
\begin{equation*}
D=\left\{z \varepsilon B^{\prime} ; \quad z \varepsilon C \bigcup \operatorname{Int}(C)\right\} \tag{6.7}
\end{equation*}
$$

$\partial D=D-\operatorname{Int}(D)$ denotes the discrete closed curve around the finite discrete domain D.

Let $f: D \rightarrow \not \subset$. Then $f$ is called a discrete function. The bibasic operators defined by Khan [1] are

$$
\begin{equation*}
D_{p x} f(z)=\frac{f(z)-f(p x, y)}{(I-p) x} \tag{6.8}
\end{equation*}
$$

$$
\begin{equation*}
D_{q y} f(z)=\frac{f(z)-f(x, q y)}{(1-q) i y} \tag{6.9}
\end{equation*}
$$

Now we define the operators $\mathrm{B}^{+}$and $\mathrm{B}^{-}$as follows.

$$
\begin{align*}
& B^{+} f(z)=\frac{1}{2}\left[D_{p x} f(z)+D_{q y} f(z)\right]  \tag{6.10}\\
& B^{-} f(z)=\frac{1}{2}\left[D_{p x} f(z)-D_{q y} f(z)\right] \tag{6.11}
\end{align*}
$$

2. DISCRETE BIBASIC PSEUDOANALYTIC FUNCTION
(a) Hölder type discrete bibasic functions

Let $D$ be a discrete domain and $f: D \longrightarrow \varnothing$. Suppose $z^{\prime}=\left(x^{\prime}, y^{\prime}\right) \varepsilon D$ and $\left|f(z)-f\left(z^{\prime}\right)\right| \leqslant k \sigma^{\mu}$ where $\sigma=\max \left\{\left(p^{-1}-1\right) x^{\prime},\left(q^{-1}-1\right) y^{\prime}\right\}$ for every $z \varepsilon A\left(z^{\prime}\right), \mu$ and $k$ are real constants $0<\mu \leqslant l$, then we say that the function $f$ is Hölder-type discrete bibasic at $z^{\prime}$.

If $f$ is Hölder-type discrete bibasic at any $z \varepsilon D$ such that $A(z) C$, then we say that $f$ is Höldertype discrete bibasic in D. The class of such functions on $D$ will be denoted by $H B(D)$.

If $D$ is a discrete domain and if $f, g \varepsilon \operatorname{HB}(D)$
then $f g \varepsilon H B(D)$
(b) Generating vector space

Let us take two discrete bibasic functions $g_{1}(z)$ and $g_{2}(z) \varepsilon H B(D)$ such that $\operatorname{Im}\left(\bar{g}_{1} g_{2}\right)>0$ throughout the discrete domain $D$. Then the row vector $g=\left[g_{1} g_{2}\right]$ is called a generating vector and the set of all generating vectors $\{g\}$ is the generating space over $D$ denoted by $G B(D)$.

The components of $g$ cannot be equal and also cannot be equal and opposite in sign.

Now if $f_{1}(z)$ and $f_{2}(z)$ are real valued functions in $D$, consider $f=\left[f_{1} f_{2}\right]^{\prime}$. The set of all such column vectors will be denoted by $\mathrm{FB}(\mathrm{D})$.

Now if $g$ is a generating vector and $W$ a discrete function defined on $D$, then for any $W$, a unique element $f \varepsilon F B(D)$ can be found such that,

$$
\begin{aligned}
W(z)= & (g . f)(z) \\
= & g_{1}(z) f_{1}(z)+g_{2}(z) f_{2}(z), \\
& \text { for all } z \varepsilon D .
\end{aligned}
$$

If possible let

$$
\begin{aligned}
W(z) & =(g . f)(z) \text { and } \\
W(z) & =(g . F)(z)
\end{aligned}
$$

Therefore $(\mathrm{g} . \mathrm{f})(\mathrm{z})=(\mathrm{g} . \mathrm{F})(\mathrm{z})$
ie.
$g_{1} f_{1}+g_{2} f_{2}-\left[g_{1} F_{1}+g_{2} F_{2}\right]=0$
ie.

$$
g_{1}\left(f_{1}-F_{1}\right)+g_{2}\left(f_{2}-F_{2}\right)=0
$$

Hence

$$
f_{1}=F_{1}, \quad f_{2}=F_{2}
$$

ie.

## fis unique.

(c) Discrete bibasic pseudoanalytic functions

Here instead of 1 and $i$ we assign two arbitrary functions $g_{1}(z)$ and $g_{2}(z)$. Hence $W(z)=G B \cdot F B(D)$ where (.) means multiplication of a row and a column vector.

Thus GB. $\mathrm{FB}(\mathrm{D})$ form a vector space over R.

We deifine

$$
\begin{align*}
& g_{p x} W(z)=\left(g \cdot D_{p x} f\right)(z)  \tag{6.13}\\
& g_{q y} D^{W}(z)=\left(g \cdot D_{q y} f\right)(z) \tag{6.14}
\end{align*}
$$

where $D_{p x}$ and $D_{q y}$ are given in (6.8) and (6.9).

## Definition

If $W$ is a discrete function defined over $D$, then $W$ is called discrete bibasic g-pseudoanalytic of the first kind at $z \varepsilon D$ if
$W \varepsilon G B \cdot F B(D)$ and $g^{D} p x^{W}(z)=g_{q y} W(z)$

If this relation holds for all $z \varepsilon D$ such that $T(z) D$, then $W$ is called bibasic g-pseudoanalytic of the first kind in D.

The class of all discrete bibasic g-pseudoanalytic functions of the first kind in $D$ is denoted by ${ }_{1} B_{D}(g)$. Then ${ }_{I} B_{D}(g)$ forms a vector space over R.

## Definition

If $W=(g . f) ; f \varepsilon F B(D), g \varepsilon G B(D)$, and $W \varepsilon{ }_{1} B_{D}(g)$, then $h=f_{1}+i f_{2}$ is called discrete bibasic g-pseudoanalytic of the second kind in $D$.

The class of all such functions of the second kind in $D$ is denoted by ${ }_{2} B_{D}(g)$.

Note
Each component $g_{1}, g_{2}$ of the generating vector is itself an element of ${ }_{1} B_{D}(g)$.

## Theorem (1)

A complex valued function $W$ will be discrete bibasic g-pseudoanalytic of the first kind in a discrete domain $D$ if and only if an $f \varepsilon F B(D)$ is found such that $\bar{B} f$ is orthogonal to $g$ throughout $D$.

## Proof

(a) Necessary

$$
\text { Suppose that } W \varepsilon_{1} B_{D}(g) \text {, then }
$$

$$
W=g . f, f \varepsilon F B(D), g \varepsilon G B(D) .
$$

Hence $\quad g^{D}{ }_{p x} W(z)={ }_{g} D_{q y} W(z)$, by (6.15)
ie.
$\left(g \cdot D_{p x} f\right)(z)=\left(g, D_{q y} f\right)(z)$ by (6.13) and (6.14)
ie.
$\left[g \cdot\left(D_{p x}-D_{q y}\right) f\right](z)=0$
ie. $\quad \frac{1}{2}\left[g \cdot\left(D_{p x}-D_{q y}\right) f\right](z)=0$
ie. $(\mathrm{g} . \overline{\mathrm{B}} \mathrm{f})(\mathrm{z})=0$ by (6.11)
ie. $\overline{\mathrm{B}} \mathrm{f}$ is orthogonal to g .
(b) Sufficient

Suppose that $W=$ g.f, $f \varepsilon F B(D), g \varepsilon G B(D)$
and $\overline{\mathrm{B}} \mathrm{f}$ is orthogonal to g , then $(\mathrm{g} . \overline{\mathrm{B}} f)(z)=0$.
ie.

$$
\frac{1}{2}\left[g \cdot\left(D_{p x}-D_{q y}\right) f\right](z)=0
$$

ie.

$$
\left(g \cdot D_{p x} f\right)(z)=\left(g \cdot D_{q y} f\right)(z)
$$

Hence by (6.15), W $\varepsilon_{I} B_{D}(g)$. Thus the theorem.

## Definition

A discrete function $f(x, y)$ is said to be biperiodic
if it is p-periodic in x and q -periodic in $\mathrm{y}, \mathrm{p} \neq \mathrm{q}, \mathrm{p}, \mathrm{q} \neq \mathrm{l}$.

## Theorem 2

$$
g^{\operatorname{DW}(z)}=0 \text { if and only if } W=(g . f)(z) \text { where } f
$$

is bi-periodic.

Proof
Let $W=g . f, g \varepsilon G B(D), f \varepsilon F B(D)$ is an element
of ${ }_{1} B_{D}(g)$. Then by (6.16)

$$
\left(g \cdot B^{-} f\right)(z)=0
$$

and

$$
\left(g \cdot B^{+} f\right)(z) \quad=\quad g^{D W(z)} .
$$

But
$\overline{B^{+} f(z)} \quad=B^{-\overline{f(z)}}$
and

$$
\begin{equation*}
\overline{B^{-} f(z)} \quad=\quad B^{-\overline{f(z)}} . \tag{6.17}
\end{equation*}
$$

Hence

$$
\left[\bar{g} \cdot\left(\overline{B^{+} f}\right)\right](z)=0
$$

ie. $\quad\left(\overline{\mathrm{g}} . \mathrm{B}^{+} \overline{\mathrm{f}}\right)(\mathrm{z})=0$ (by 6.17)
ie. $\left(\bar{g} \cdot B^{+} f\right)(z)=0$, since $f$ is real valued.

Thus we get,

$$
g_{1}(z) B^{+} f_{1}(z)+g_{2}(z) B^{+} f_{2}(z)=g^{D W(z)}
$$

and

$$
\overline{g_{1}(z)} B^{+} f_{1}(z)+\overline{g_{2}(z)} B^{+} f_{2}(z)=0
$$

Solving
and $\quad B^{+} f_{2}(z)=\frac{-\overline{g_{1}(z)} g^{D W(z)}}{g_{1}(z) \overline{g_{2}(z)-\overline{g_{1}(z)} g_{2}(z)}}$.

If $g^{\mathrm{DW}}(\mathrm{z})=0$, then (6.18) and (6.19) we have

$$
B^{+} f_{1}(z)=0=B^{+} f_{2}(z)
$$

ie.

$$
\left(D_{p x}+D_{q y}\right) f_{I}(z)=0
$$

and

$$
\left(D_{p x}+D_{q y}\right) f_{2}(z)=0 .
$$

Hence

$$
\frac{f_{1}(z)-f_{1}(p x, y)}{(1-p) x}+\frac{f_{1}(z)-f_{1}(x, q y)}{(1-q) i y}=0
$$

and

$$
\frac{f_{2}(z)-f_{2}(p x, y)}{(1-p) x}+\frac{f_{2}(z)-f_{1}(x, q y)}{(l-q) i y}=0
$$

since $f_{1}$ and $f_{2}$ are real valued, equating real and imaginary parts to zero, we have

$$
\begin{aligned}
& f_{1}(z)-f_{1}(p x, y)=0 \\
& f_{1}(z)-f_{1}(x, q y)=0 \\
& f_{2}(z)-f_{2}(p x, y)=0 \\
& f_{2}(z)-f_{2}(x, q y)=0
\end{aligned}
$$

Hence $f$ is bi-periodic, ie. p-periodic in $x$ and $q$-periodic in y .
(b) Sufficiency

Suppose that $W=(g . f), g \varepsilon G B(D), f \varepsilon F B(D)$
is an element of ${ }_{I} B_{D}(g)$ and $f$ is bi-periodic.

$$
\begin{aligned}
g^{D W(z)} & =\left(g \cdot B^{+} f\right)(z) \\
& =g \cdot \frac{1}{2}\left(D_{p x} f+D_{q y} f\right)(z) \\
& =0 .
\end{aligned}
$$

since $f$ is p-periodic in $x$ and $q$-periodic in $y$.
Hence the theorem.

## Remark

Solutions of the equation, $g^{D W}(z)=0$ are called g-pseudo constants. We can represent a g-pseudoconstant by g.f where $f$ is p-periodic in $x$ and q-periodic in $y$.
3. DEDUCTIONS
(1) The discrete bibasic pseudo-analytic function theory developed here is a two fold extension of the theory of discrete basic pseudo analytic functions in the following sense.

The two variables of the function run on two different bases as against one in the discrete basic pseudoanalytic function theory. Thus for $p=q<1$, q-pseudoanalytic function theory becomes a particular case of this.
(2) When $\mathrm{B}^{-} \mathrm{f}(\mathrm{z})$ of (6.11) becomes zero, the discrete pseudoanalytic function theory reduces to Khans [I] bibasic analytic function theory.
(3) When $\mathrm{p}=\mathrm{q}^{-1}$ in the second case, we get Velukutty's [l] bianalytic functions where $0<q<1$.
(4) If further $p=q<I$ and $B^{-} f(z)=0$, then this reduces to Harmans [1] q-analytic function theory.

## 4. EXAMPLES OF BIBASIC ANALYTIC FUNCTIONS

Harman [I] defined $z^{(n)}$ with base $q$ by using continuation operator as,

$$
\begin{equation*}
z^{(n)}=\sum_{j=0}^{n} \frac{(1-q)_{n}}{(1-q)_{n-j}^{(1-q)_{j}}}(i y)^{j} x^{n-j} \tag{6.20}
\end{equation*}
$$

This is q-analytic. Khan [I] defined $z^{(n)}$ with bases p and q , as the following

$$
\begin{equation*}
z^{(n)}=\sum_{j=0}^{n} \frac{(p)_{n}}{(p)_{n-j}(q)_{j}}\left\{\frac{(1-q) i y}{1-p}\right\}^{j} x^{n-j}, \tag{6.21}
\end{equation*}
$$

where

$$
\begin{equation*}
D_{p x^{z}}(n)=D_{q y^{2}}\left(\frac{1-p^{n}}{1-p}\right) z^{(n-1)} \tag{6.22}
\end{equation*}
$$

This analogue of ${ }_{z}(n)$ suffers from a disadvantage that $D_{p x} z^{(n)}$ and $D_{q y^{z}}{ }^{(n)}$ are both given in terms of $p$. We define $z^{(n)}$, using the same bibasic lattice $\left\{\left(p^{m} x_{0}, q^{n} y_{0}\right)\right.$, given in (6.1) as

$$
\begin{aligned}
z^{(n)} & =V[n]_{p}![n]_{q}!\quad \sum_{r=0}^{n} \frac{x^{n-r}(i y)^{r}}{[n-r]_{p}![r]_{q}!} \\
& =\sqrt{[n]_{p}![n]_{q}!} \sum_{r=0}^{n} \frac{x^{r}(i y)^{n-r}}{[r]_{p}^{!}[n-r]_{q}^{!}}
\end{aligned}
$$

which removes this difficulty. We now prove that $z^{(n)}$ is bibasic analytic.

## Theorem 3

$$
z^{(n)}=V[n]_{p}![n]_{q}!\quad \sum_{r=0}^{n} \quad \frac{x^{n-r}(i y)^{r}}{[n-r]_{p}![r]_{q}}:
$$

is bibasic analytic in $D$.

## Proof

$$
\begin{aligned}
& D_{p z^{2}} z^{(n)}=D_{q y^{(n)}} z^{(n)} \text {. }
\end{aligned}
$$

Consider

$$
D_{p x^{z}}^{(n)}=D_{p x} V[n]_{p}:[n]_{q}: \sum_{r=0}^{n} \frac{x^{n-r}(i y)^{r}}{[n-r]_{p}:[r]_{q}}:
$$

$$
=V[n]_{p}:[n]_{q}: \sum_{r=0}^{n} \frac{(i y)^{r}}{[n-r]_{p}![r]_{q}}:\left\{\frac{x^{n-r}-p^{n-r} x^{n-r}}{(1-p) x}\right\}
$$

$$
\left.=V[n]_{p}^{[n]}\right]_{q} V[n-1]_{p} ;[n-1]_{q}: \sum_{r=0}^{n-1} \frac{x^{n-r-1}(i j)^{r}}{[n-r-1]_{p}![r]_{q}!}
$$

$$
\begin{equation*}
=V[n]_{p}[n]_{q} z^{(n-1)} \tag{6.24}
\end{equation*}
$$

Now,

$$
D_{q y} z^{(n)}=V[n]_{p}:[n]_{q}: \sum_{r=0}^{n} \frac{x^{n-r}}{[n-r]_{p}:[r]_{q}}:\left\{\frac{(i y)^{r}-q^{r}(i y)^{r}}{(1-q) i y}\right\}
$$

$$
\begin{align*}
& =V[n]_{p}[n]_{q} V[n-1]_{p}:[n-1]_{q}: \sum_{r=0}^{n} \frac{x^{n-r}(i y)^{r-1}}{[n-r]_{p}:[r-1]_{q}}: \\
& =V[n]_{p}[n]_{q} V[n-1]_{p}:[n-1]_{q}: \sum_{r=0}^{n-1} \frac{x^{n-1-r}(i y)^{r}}{[n-1-r]_{p}![r]_{q}}: \\
& =V[n]_{p}[n]_{q} z^{(n-1)} . \tag{6.25}
\end{align*}
$$

From (6.24) and (6.25) we get,

$$
D_{p z} z^{(n)}=D_{q y^{2}}(n)=V[n]_{p}[n]_{q} z^{(n-1)}
$$

Hence $z^{(n)}$ is bibasic analytic in $D$. Also $z^{(0)}=1$.

## Exporential function

Here we define the bibasic analogie of the exponential function as

$$
\begin{equation*}
\operatorname{bex}(z)=\sum_{r=0}^{\infty} \frac{z^{(r)}}{V[r]_{p}![r]_{q}!} \tag{6.26}
\end{equation*}
$$

where $z$ is given by (6.23).

## Theorem 4

bex(z) is dibasic analytic in $D$.

## Proof

Let $z \varepsilon$ D.

Then

$$
D_{p x} \operatorname{bex}(z)=D_{p x} \sum_{r=0}^{\infty} \frac{z^{(r)}}{\sqrt{[r]}]_{p}![r]_{q}!}
$$

$$
=\sum_{r=1}^{\infty} \frac{1}{V[r]_{p}![r]_{q}!} \quad V[r]_{p}[r]_{q} z^{(r-1)}
$$

$$
=\sum_{r=1}^{\infty} \frac{z^{(r-I)}}{\sqrt{[r-1]_{p}![r-1]_{q}}!}
$$

$$
=\sum_{r=0}^{\infty} \frac{z^{(r)}}{\sqrt{[r]_{p}![r]_{q}}}
$$

$$
D_{q y} \operatorname{bex}(z)=\sum_{r=1}^{\infty} \frac{z^{(r-1)}}{\sqrt{[r-1]_{p}![r-1]_{q}}!}
$$

$$
=\sum_{r=0}^{\infty} \frac{z^{(r)}}{V[r]_{p}![r]_{q}!}
$$

Hence bex(z) is dibasic analytic in D.
Now we show that $z^{(n)}$ satisfy Laplace's equation.

$$
\begin{aligned}
& D_{p x^{z}}^{(n)}=V[n]_{p}[n]_{q} z^{(n-1)} \text { by (6.24) } \\
& D_{p x}{ }^{2} z^{(n)}=V[n]_{p}[n]_{q} V[n-1]_{p}[n-1]_{q} z^{(n-2)},(6.27)
\end{aligned}
$$

Similarly,

$$
\begin{equation*}
D_{q y}^{2} z^{(n)}=V[n]_{p}[n]_{q} V[n-1]_{p}[n-1]_{q} z^{(n-2)} \tag{6.28}
\end{equation*}
$$

From (6.27) and (6.28) we get.

$$
\left(D_{p x}^{2}-D_{q y}^{2}\right) z^{(n)}=0
$$

In a similar manner we get,

$$
\left(D_{p x}^{2}-D_{q y}^{2}\right) \operatorname{bex}(z)=0
$$

5. DISCRETE BIBASIC ANALYTIC CONTINUATION

Harman [1] has extended the discrete plane to include points on the positive half axes, and has shown that continuation into $Q^{\prime}$ from both the axes is possible. Here taking a similar approach we consider continuati on

(a) The bibasic operator $\operatorname{Lf}(z)=\{[z-p x+i q y] f(z)$ $-(1-p) \times f(x, q y)+(1-q)$ iy $f(p x, y)\}$, defined by Khan[I] involves a bibasic triad of points

$$
T(z)=\{(x, y),(p x, y),(x, q y)\} .
$$

From these it follows that given the value of a bibasic analytic function $f$ at any two points of $T(z)$, then it is uniquely determined at the third point.
(b) Hence, if a bibasic analytic function $f$ is defined at the set of points $\left\{\left(p^{m} x, y\right) ; m \varepsilon Z\right\}$, then it can be uniquely continued as a bibasic analytic function to all points of $B^{\prime}$ lying below this set of points.
(c) Similarly continuation is possible from $\left\{\left(x, q^{n} y\right) ; n \in Z\right\}$.
(d) If $f$ is defined on the sets $\left\{\left(p^{m} x, y\right) ; m \varepsilon z\right\}$ and $\left\{\left(x, q^{n} y\right) ; n \in Z\right\}$, then it has a qnique continuation as a bibasic analytic function to all points of $B^{\prime}$.
(e) If $f$ is defined on the $\operatorname{sets}\left\{\left(p^{m}, y\right) ; m=0,1,2, \ldots\right\}$ and $\left\{\left(x, q^{n} y\right) ; n=0,1,2, \ldots\right\}$, then by repeated application of (a), the function has unique continuation into the rectangular region $\left\{\left(p^{m}, q^{n} y\right) ; m=0,1, \ldots ; n=0,1, \ldots\right\}$.
(f) Let $X=\left\{\left(p^{m} x_{0}, 0\right) ; m \varepsilon z\right\}$

$$
\mathrm{Y}=\left\{\left(0, \mathrm{q}^{\mathrm{y}_{0}}\right) ; \mathrm{n} \varepsilon \mathrm{z}\right\},
$$

where ( $x_{0}, y_{0}$ ) is the fixed point of definition of $B^{\prime}$. by (6.1). Then we define *he extended discrete plane

$$
\bar{B}=B^{\prime} \bigcup X \bigcup Y .
$$

The discrete rectangular domain $R^{\prime}$ is defined by

$$
R^{\prime}=\left\{\left(p^{m} x_{0}, q^{n} y_{0}\right) ; m=0,1, \ldots ; n=0,1, \ldots\right\}
$$

If $\mathrm{X}^{+}, \mathrm{Y}^{+}$are defined by
then the extended rectangular domain $R$ is defined as

$$
\begin{equation*}
\bar{R}=R^{\prime} \bigcup X^{+} \bigcup Y^{+} . \tag{6.29}
\end{equation*}
$$

The values on the axes, of a discrete function $f$ defined on $R^{\prime}$ are defined to be

$$
\begin{aligned}
f(x, 0) & =\lim _{n \rightarrow \infty} f\left(x, q^{n} y_{0}\right)=\lim _{y \rightarrow \infty} f(x, y) \\
f(0, y) & =\lim _{m \rightarrow \infty} f\left(p^{m} x_{0}, y\right)(x, y) \varepsilon R^{\prime} \\
& =\lim _{x \rightarrow 0} f(x, y) .
\end{aligned}
$$

Now we define the continuation operators as follows,

$$
\ell_{p x}[f(0, y)]=\sum_{j=0}^{\infty} \frac{1}{[j]_{p}} x^{j} D_{q y}^{j}[f(0, y)]
$$

$$
\hat{G}_{q y}[f(x, 0)]=\sum_{j=0}^{\infty} \frac{1}{[j]_{q}!}(i y)^{j} D_{p x}^{j}[f(x, 0)]
$$

To verify these definitions we consider $z^{(n)}$ by continuation.

$$
\begin{aligned}
\ell_{q y} f[(x, 0)] & =\sum_{j=0}^{\infty} \frac{1}{[j]_{q}!}(i y)^{j} D_{p x}{ }^{j}\left[V[n]_{p}![n]_{q}!\frac{x^{n}}{[n]_{p}!}\right] \\
& =\sqrt{\frac{[n]_{q}!}{[n]_{p}!} \sum_{j=0}^{\infty} \frac{1}{[j]_{q}!}(i y)^{j} D_{p x}^{j}\left(x^{n}\right)} \\
& =\sqrt{\frac{[n]_{q}!}{[n]_{p}!}} \sum_{j=0}^{n} \frac{1}{[j]_{q}!}(i y)^{j} \frac{[n]_{p}:}{[n-j]_{p}!} x^{n-j}
\end{aligned}
$$

since $D_{p x}^{j}=0$ when $j>n$.

$$
\begin{equation*}
=V[n]_{p}:[n]_{q}: \sum_{j=0}^{n} \frac{x^{n-j}(i y)^{J}}{[j]_{q}:[n-j]_{p}}: \tag{6.30}
\end{equation*}
$$

Now again,

$$
\begin{aligned}
\ell_{p x}[f(0, y)] & =\sum_{j=0}^{\infty} \frac{1}{[j]_{p}!} x^{j} D_{q y}^{j}[f(o, y)] \\
& =\sum_{j=0}^{n} \frac{1}{[j]_{p}!} x^{j} D_{q y}^{j}\left[V[n]_{p}:[n]_{q}: \frac{(i y)^{n}}{[n]_{q}!}\right]
\end{aligned}
$$

$$
=\sqrt{\frac{[n]_{p}!}{[n]_{q}!}} \sum_{j=0}^{n} \frac{1}{[j]_{p}!} x^{j} \frac{[n]_{q}}{[n-j]_{q}}:(i y)^{n-j},
$$

since $D_{q y}^{j}(i y)^{n}=0$ for $j>n$.

$$
\begin{equation*}
=V[n]_{p}![n]_{q}!\sum_{j=0}^{n} \frac{x^{j}(i y)^{n-j}}{\left[n-j_{q}![j]_{p}\right.}! \tag{6.31}
\end{equation*}
$$

From (6.30) amd (6.31) we see that continuation operators can be used to derive $f(z)$ sirce (6.30) and (6.31) are equal to $z^{(n)}$ of (6.23). In a similar mariner we can extend the exponential function using continuation operators.

## 6. DISCRETE BIBASIC MACLAURIN SERIES

We can find an analogue for the Maclaurin series about the point $z_{0}=0$. To include the point ( 0,0 ), we extend the definition of $\overline{\mathrm{R}}$ of (6.29) as follows,

$$
\begin{equation*}
\overline{R_{0}} \quad=\bar{R} \bigcup(0,0) \tag{6.32}
\end{equation*}
$$

A discrete function $f$ is said to be bibasic analytic on
$\overline{\mathrm{R}}_{\mathrm{o}}$ if it is bibasic analytic on $\overline{\mathrm{R}}$ and in addition

$$
\lim _{(x, y)} \longrightarrow(o, o) D_{p q}^{j}[f(x, y)]
$$

exists and the limit is denoted by $D_{p q}^{j} f(o, o)$.

Under certain conditions the discrete Maclaurin series can be shown to represent a bibasic-analytic function, provided, the series converges. We consider the following.

Theorem 5
Let $f$ be bibasic analytic in $\bar{R}_{0}$. If $f(z)=$ $\ell_{q y} f(x, 0)=\ell_{p x} f(0, y)$, the series representations of $f_{\mathrm{q} y}, l_{\mathrm{px}}$, being absolutely convergent in $\overline{R_{0}}$, then

$$
\begin{equation*}
f(z)=\sum_{j=0}^{\infty} \frac{D_{p q}{ }_{f(0,0)} z^{(j)}}{V[j]_{p}![j]_{q}!}, \tag{6.33}
\end{equation*}
$$

the series being absolutely convergent for all $z \varepsilon \bar{R}_{0}$.
Proof

$$
f(z)=b_{\mathrm{px}}[f(0, y)]
$$

$$
=\sum_{j=0}^{\infty} \frac{1}{[j]_{p}!} x^{j} D_{q y}^{j}[f(0, y)]
$$

Hence,

$$
\begin{aligned}
f(x, 0) & =\lim _{y \rightarrow 0} \sum_{j=0}^{\infty} \frac{I}{[j]_{p}!} x^{j} D_{q y}^{j}[f(0, y)] \\
& =\sum_{j=0}^{\infty} \frac{1}{[j]_{p}!} x^{j} D_{p q}^{j}[f(0,0)] .
\end{aligned}
$$

Also, $f(z)=\log _{\mathrm{q}} \mathrm{f}(\mathrm{x}, 0)$

$$
=\sum_{j=0}^{\infty} \frac{1}{[j]_{q}!}(i y)^{j} D_{p x}^{j} f(x, 0) .
$$

hence,

$$
\begin{aligned}
f(z) & =\sum_{j=0}^{\infty} \frac{1}{[j]_{q}!}(i y)^{j} D_{p x}^{j} \sum_{k=0}^{\infty} \frac{1}{[k]_{p}!} x^{k} D_{p q}^{k} f(o, o) \\
& =\sum_{j=0}^{\infty} \frac{1}{[j]_{p}![j]_{q}!} D_{p q}^{j} f(0,0) \sum_{k=0}^{j} \frac{[j]_{p}!}{[j-k]_{p}!} x^{j-k}(i y)^{j}
\end{aligned}
$$

$$
\begin{aligned}
& =\sum_{j=0}^{\infty} \frac{D_{p q}^{j} f(0,0)}{V[j]_{p}![j]_{q}!} \sum_{k=0}^{j} \frac{V[j]_{p}![j]_{q}!}{[j-k]_{p}![j]_{q}!}(i y)^{j} x^{j-k} \\
& =\sum_{j=0}^{\infty} \frac{D_{p q}^{j} f(o, o)_{z}(j)}{V[j]_{p}![j]_{q}!} .
\end{aligned}
$$

Hence the result.
If $\lim \sup \left\{\left|D_{p q}^{j} f(0,0)\right|^{l / j}\right\}=a$, then the series (6.33)
converges absolutely for all $Z_{z}$ such that

$$
\|z\|<\frac{1}{a}\left[\frac{1}{1-q}+\frac{]}{1-p}\right]
$$

using the similar approach of Harman [1]. We can prove that the series representations $\log _{q y}, \log _{\mathrm{px}}$ are uniformly and absolutely convergent in $\overline{R_{0}}$.

Only a limited treatment of power series has been carried out in the discrete analytic function theory. The form of $z^{(n)}$ and bex(z) of (6.23) and (6.26) suggests that further extensions should be possible. But a suitable convolution operator is to be defined. Of fundamental importance to such a study would be the determination of suitable bounds for the function $D_{p q}^{j}\left[f\left(z_{0}\right)\right]$. This may then lead to general conditions for the convergence of discrete power series.

## CONCLUDING REMARKS

In this thesis an attempt has been made to establish a theory of basic and bibasic commutative difference operators, solution of basic and bibasic difference equations, and bibasic pseudoanalytic functions. Classical analysis, q-theory, bibasic theory, q-analytic function theory, bibasic analytic function theory, discrete pseudoanalytic function theory, have been utilised to develop the above concepts.

We have proved that two operators $P_{m}$ and $Q_{n}$ are commutative if and only if the characteristic equation $F\left(P_{m}, Q_{n}\right)=0$ is satisfied. But this can be proved by using integral curves on the lines of J.L. Burchnall and T,W. Chaundy $[2,3]$ where Abeliai coefficients occur.

We have used some commutative operators to solve basic and bibasic difference equations. There are some interesting problems related to these theories like study of integral curves and second degree partial difference equations which we have not been attempted here.

Only some properties of bibasic analytic
functions have been established here. But the technique can be used for deeper study of such functions.

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